Generalized Entangled-Photon Imaging

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ABSTRACT - When one of a pair of entangled photon beams is transmitted through an object, coincidences with photons in the other beam contain information about the object. We present a generalized formulation for a coded-aperture imaging system using this effect.

Entangled-photon beams generated by parametric downconversion have been used in numerous experiments to test the foundations of quantum mechanics. A variety of practical applications have also been demonstrated using such beams, including absolute radiometric measurements, quantum cryptography, and quantum imaging [1,2]. This paper provides a generalized formulation of the quantum imaging problem. We derive an expression for the photon coincidence rate after each of a pair of entangled photon beams has been transmitted through a separate general linear optical system, one of which contains the unknown object. We examine the retrievability of the object information from a measurement of the coincidence rate.

Consider the overall system illustrated in Fig. 1. A source S emits pairs of entangled photons in two beams, the signal and the idler. The signal photons are transmitted through an object O and are collected by a detector \mathcal{D}_1 after passing through an arbitrary optical system \mathcal{A} . The idler photons are transmitted through an optical system \mathcal{B}_n and are collected by a detector \mathcal{D}_2 . The photon coincidence rate C_n is measured with various optical systems \mathcal{B}_n ,

n=1,2,..., in place. The systems \mathcal{B}_n may represent, for example, a set of coded apertures, or a displaced pinhole. The idea is to extract information about the object O from measurements of the coincidence rate C_n for various optical systems \mathcal{B}_n , n=1,2,...

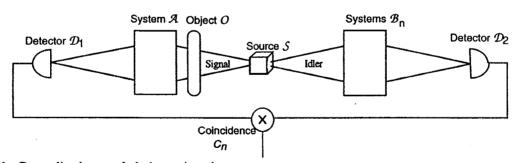


Fig. 1 Generalized entangled-photon imaging system.

To be specific, asssume that O is a thin planar object with complex amplitude transmittance f(x), and for simplicity assume that the object and the optical systems are both one-dimensional. Classically, the fields E_1 and E_2 at the detectors \mathcal{D}_1 and \mathcal{D}_2 are related to the fields $E_s(x)$ and $E_i(x)$ at the inputs to the object O and to the system \mathcal{B}_n , respectively, by the linear integrals

$$E_1 = \int A(x)f(x)E_s(x)dx$$

$$E_2 = \int B_n(x)E_i(x)dx,$$
(1)

where A(x) and $B_n(x)$ are appropriate weighting factors determined from the impulse response functions of the systems \mathcal{A} and \mathcal{B}_n . The most general state of a photon pair at these input planes is

$$|\Psi\rangle = \iint dx dx' g(x, x') \hat{a}_s^+(x) \hat{a}_i^+(x') |0, 0\rangle, \qquad (2)$$

where $|0,0\rangle$ represents the vacuum state and $\hat{a}_s^+(x)$ and $\hat{a}_i^+(x')$ are the photon creation operators for the signal and idler at positions x and x', respectively. For simplicity we have assumed further that the signal and the idler are monochromatic. All of the characteristics of the source are encoded in the correlation function g(x,x'). If we are not interested in resolution on the scale of the wavelength of the photons, we may consider that the creation and annihilation operators for different space points commute, i.e., $\left[\hat{a}_s^+(x), \hat{a}_s^-(x')\right] = \delta(x-x')$, and similarly for the idler photons.

The coincidence rate $C_n = \left\langle \Psi \middle| \hat{E}_1 - \hat{E}_2 - \hat{E}_2 + \hat{E}_1 \middle| \Psi \right\rangle$ can now be determined by straightforward use of the previous equations. This readily leads to the principal equation of this paper:

$$C_n = \left| \iint g(x, x') f(x) A(x) B_n(x') dx dx' \right|^2. \tag{3}$$

This equation relates the coincidence rate C_n to the unknown object transmittance f(x), through the known functions A(x), $B_n(x)$, and g(x,x'), which determine the kernel of the transformation. The coincidence rates $\{C_n\}$ are therefore the squared magnitudes of linear projections of the unknown function f(x).

The ideal case in which $g(x,x') = \delta(x-x')$, i.e., the photons are perfectly entangled, is particularly revealing. In this case, Eq. (3) gives

$$C_n = \left| \int f(x)A(x)B_n(x)dx \right|^2. \tag{4}$$

Moreover, since A(x) and $B_n(x)$ are simply multiplied under the integral, the systems \mathcal{A} and \mathcal{B}_n are exchangeable. This may be important in practical situations where optical components cannot be placed in the vicinity of the object. The entangled-photon imaging system therefore offers the flexibility of obtaining the same effect by placing a complex optical apparatus in the idler beam, away from the object.

Suppose now that A(x) = 1, i.e., that the \mathcal{A} system simply directs the rays of the signal beam onto \mathcal{D}_1 . Equation (4) then becomes

$$C_n = \left| \int f(x) B_n(x) dx \right|^2 \tag{5}$$

If the $\{B_n(x)\}$ form a complete set of orthonormal functions, then the $\{C_n\}$ are simply the squared magnitudes of the coefficients of an expansion of the unknown function f(x) in this basis. Under special conditions, the phases can be retrieved, and the function f(x) completely reconstructed.

The special case in which $B_n(x) = \delta(x - x_n)$, i.e., when the system \mathcal{B}_n samples the idler field at positions x_n , has been demonstrated experimentally by using a scanning system [1]. In our case, Eq. (5) then provides $C_n = |f(x_n)|^2$ so that the coincidence rate yields the *intensity* transmittance of the object.

Consider now a system \mathcal{B}_n that collects light from two pinholes: $B_n(x) = \delta(x) + \delta(x - x_n)$. Such system has been recently demonstrated [2]. Here Eq. (5) gives $C_n = |f(0) + f(x_n)|^2$. As x_n is scanned, the coincidence rate C_n provides the same interference pattern that would have been obtained if the object were illuminated with coherent light and viewed through pinholes located at x = 0 and $x = x_n$. The phase of the function f(x) can in principle be reconstructed up to a constant phase, the phase of f(0). With the magnitude and phase of f(x) determined, complete knowledge of the object is retrieved.

In conclusion, Eq. (3) shows that complex object information is encoded in the measured coincidence rate. By appropriate choices of the systems functions A(x) and $B_n(x)$, such information can be extracted. Deviation of the function g(x,x') from a delta function, resulting from partial entanglement [3], plays a key role in limiting the resolution of this imaging system. This effect is mathematically analogous to the effect of partial coherence in ordinary imaging systems.

References

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