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Multiple-Frequency Heterodyne Correlation Radiometry

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Abstract

A heterodyne correlation radiometer is proposed for the sensitive detection of radiating species whose Doppler shift is known, but whose presence we wish to affirm. Such radiation (which may be actively induced) can arise, for example, from remote molecular emitters, impurities and pollutants, trace minerals, chemical agents, or a general multiline source. A radiating sample of the species to be detected is physically made a part of the laboratory receiver, and serves as a kind of frequency-domain template with which the remote radiation is correlated, after heterodyne detection. The system is expected to be especially useful for the detection of sources whose radiated energy is distributed over a large number of lines, with frequencies that are not necessarily known. Neither a stable nor a tunable local oscillator is required. It is shown that the minimum detectable power is expressible in a form similar to that for conventional heterodyning (for both quantum-noise-limited and Johnson-noise-limited detectors). The notable distinction is that the performance of the proposed system improves with increasing number of remotely radiating signal lines and increasing locally produced radiation power. Performance degradation due to undesired impurity radiation is considered and shown not to be a problem in general. The technique should be applicable over a broad frequency range from the microwave to the optical, with its most likely use in the infrared.

I. Introduction

In a recent series of papers, three-frequency nonlinear heterodyne detection has been shown to be a useful technique for the acquisition of weak communications and radar signals in the presence of substantial Doppler shift. The same concept has also been considered in the context of a multiple-frequency passive configuration, for the selective heterodyne detection of radiation from known remote species moving with unknown velocities. Basically, the system uses a nonlinear element to provide an output signal near a predetermined difference frequency, which is independent of the Doppler shift of the received signals. The quantity may be the frequency difference between two transmitter modes, or the rest difference frequency between two waves emitted from a remotely radiating molecule. The signal-to-noise ratio (SNR) obtainable with the nonlinear heterodyne system can be substantially higher than that obtainable with a conventional heterodyne system by virtue of the (often considerable) decrease in receiver bandwidth that is possible and the small amount of receiver noise introduced by the nonlinear element.

In this paper, we propose the use of the same principle in an altered configuration, to sensitively detect the signature of a (molecular) species whose Doppler feature is known, but whose presence we wish to affirm. A radiating sample of the species to be detected is physically made a part of the laboratory receiver, and serves as a kind of frequency-domain template with which the remote radiation is correlated, after heterodyne detection. The system will be especially useful for the detection of molecules whose radiated energy is distributed over a large number of lines, with frequencies that are not necessarily known. Examples include the radiation from complex molecules at submillimeter wavelengths and molecular radiation in the infrared and optical. We observe that remote conventional heterodyne radiometry and spectroscopy have recently begun to find use at these higher frequencies. Abbas et al. have recently performed a detailed investigation of the sensitivity limits of a real infrared heterodyne spectrometer for astrophysical use.

II. System Configuration

A block diagram of the remote-detection version of the proposed system is illustrated in Figure 1. The remotely radiating source emits electromagnetic radiation at a series of rest signal frequencies \( f_j \) (j integer). Also present in the same source are other undesired species (impurities), emitting radiation at the series of rest frequencies \( f_k \) (k integer). The \( f_j \) radiation, as well as the \( f_k \) radiation, will in general be Doppler shifted due to the mass motion (Doppler feature) of the source, and will arrive at the receiving station with frequencies \( f'_j \) and \( f'_k \), respectively. By analogy, these

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Fig. 1  Block diagram for the heterodyne correlation radiometer. Dotted lines represent radiation signals, solid lines with arrows represent electrical signals, and dashed lines enclose one version of a Dicke radiometer that can be added to the system if required.

series are referred to as \( J' \) and \( K' \). Assuming that the velocity of the cloud is much smaller than the speed of light \( c \), the nonrelativistic Doppler formula provides

\[
    f'_{j} = f_{j}(1 \pm v_{\parallel}/c) \quad \text{(1a)}
\]

and

\[
    f'_{k} = f_{k}(1 \pm v_{\parallel}/c), \quad \text{(1b)}
\]

where \( v_{\parallel} \) is the radial component of the over-all velocity vector \( \mathbf{v} \) (see Figure 1). Individual lines will also be broadened in general, due to the constituent particle velocity spectrum.

The received remote radiation is then combined with the radiation from a local sample of the species to be detected, which is at rest in the laboratory frame and therefore emits at frequencies \( f_{j} \). The three series of frequencies \( (f'_{j}, f_{j}, f_{k}) \) are mixed in a heterodyne detector with a strong, coherent, and polarized local oscillator (LO) signal at frequency \( f_{L} \) to produce three series of strong electrical beat signals at \( |f'_{j} - f_{L}| \), \( |f_{j} - f_{L}| \), and \( |f'_{k} - f_{L}| \), along with a dc component that is blocked. Signals at \( |f'_{j} - f_{L}| \), \( |f'_{k} - f_{L}| \), and \( |f_{j} - f_{L}| \), arising without benefit of the LO, are weak and may be neglected. In the infrared and optical, optimum mixing requires coincident, plane, parallel, and polarized waves normally incident on the photodetector; thus spatial first-order coherence is required over the detector aperture.\(^{10-14}\) The ac output of the heterodyne mixer must then be coupled through a filter of bandwidth \( \Delta f \), to a nonlinear device. Provided that the bandwidth \( \Delta f \) encompasses several lines produced by the species to be detected, its value is not critical as we shall see shortly. The nonlinear device, which is assumed to have a response over \( \Delta f \), then generates a component of power at the Doppler shift frequency

\[
    |f'_{j} - f_{j}| = (v_{\parallel}/c)f_{j} \quad \text{(2)}
\]

for each \( j \) when both \( |f'_{j} - f_{L}| \) and \( |f_{j} - f_{L}| \) pass through \( \Delta f \). The greater the number \( n \) of these line pairs that pass through, the greater the power generated at the Doppler shift frequency.
Previous embodiments of this system generally assumed that the Doppler shift (represented by \( \nu_0 \)) was unknown within broad limits, but that the difference frequency \( f_c \) was known a priori to high accuracy. In the present circumstance, we assume that the radiated line frequencies are unknown but that the Doppler shift (\( \nu_0 \)) is known a priori, at least to good approximation. As previously\(^1\)-\(^5\) the nonlinear device output is independent of LO frequency and amplitude fluctuations, within broad limits. A careful choice of the LO frequency may sometimes be useful, however.) A narrowband filter centered at \( |f_j - f_{0j}| \) and of bandwidth \( B \), placed after the nonlinear device, achieves a low noise bandwidth. Only the heterodyne mixer and the nonlinear device need have high-frequency response in many instances. Thus, amplifiers and other detection apparatus following the nonlinear device, though omitted in the block diagram for simplicity, process electrical signals at (usually) moderate frequencies, which provides ease of matching as well as good receiver noise figure. This, in turn, decreases the LO power necessary for optimum coherent detection\(^12\)-\(^14\). The effects of accidental contributions at \( |f_j - f_{0j}| \) arising from the \( \Omega^1 \) series can generally be neglected, as we will see later.

If warranted, the output of the narrow bandpass filter may be fed into a standard Dicke radiometer\(^15\)-\(^17\), \(^7\)-\(^9\) (dashed box in Figure 1) consisting of a (third) detector, a phase-sensitive (synchronous) detector, and an integrator with time constant \( \tau \). Although we specify that the third detector is square-law in Figure 1, its characteristic is not critical and, in fact, a linear detector will often provide the cleanest signal. The modulation may be obtained from a chopper as indicated in Figure 1, though in some circumstances it might be advantageous to chop the locally produced radiation instead of the remote radiation. The use of a Dicke radiometer can sometimes provide improvement in the SNR and has been coupled with conventional infrared heterodyne systems in a number of instances\(^6\)-\(^9\). It may also be advantageous to use a balanced mixer in this configuration\(^6\).

### III. Calculation of the Ideal SNR

The SNR at the output (0) of the heterodyne correlation radiometer (SNR\(_0\)) is given by [see Eqs. (45) and (77) of Ref. 2, and Eq. (4) of Ref. 4]

\[
(SNR)_0 = \rho \{\text{SNR} \}_{i}^{3}/[1+2(SNR)_{i}],
\]

(3)

assuming the use of a coherent LO that produces no excess noise, a bandpass filter close to low-pass (\( \Delta f = f_{0i} \)), and a square-law nonlinear device (for which it is easy to carry out the calculation). Here \( (SNR)_{i} \) represents the SNR at the input (i) to the square-law device (see Figure 1) and will often be \( \ll 1 \). For the particular cases examined previously\(^1\)-\(^4\) the constant \( \rho \) is bounded by \( 1 \leq \rho \leq 2 \) for LO frequencies such that \( f_{L} \ll |f_{j} - f_{0j}| \) or \( f_{L} = |f_{j} - f_{0j}| \), which is the usual situation. Only in certain special cases does \( \rho \) exceed 2.\(^4\), \(^5\)

For the multiple-frequency nonlinear heterodyne configurations considered earlier\(^1\)-\(^4\) the quantity \( \kappa \) was shown to depend on the magnitude and on the statistical and spectral nature of the received radiation, as well as on the widths of the two bandpass filters. Calculations for \( \kappa \) have been carried out for the heterodyne correlation radiometer considered here (see Appendix A), and the results turn out to be similar to those obtained previously [see Eq. (5) of Ref. 4]. A number of specific cases are of interest: sinusoidal signals (s), independent Gaussian signals with Gaussian spectra (g), and independent Gaussian signals with Lorentzian spectra (l). The Gaussian case is particularly important since radiation from astronomical sources is generally Gaussian\(^19\). For these cases, \( \kappa \) is given by (see Appendix A)

\[
\kappa_s = \frac{f}{B} \left[ \sum_{j=1}^{n} \frac{A_j^2 A_j^2}{\{ n \sum_j A_j^2 + \sum_k A_k^2 \}^{1/2}} \right],
\]

\[\text{(4a)}\]

\[
\kappa_g = \frac{f}{B/\sqrt{2}} \left[ \sum_{j=1}^{n} \frac{(\nu P_j)(\nu P_{j'})}{\{ n \sum_j (\nu P_j)(\nu P_{j'}) + \sum_{k=1}^{\infty} \nu P_{k}^2 \}^{1/2}} \right] \left( \frac{2\pi (B/\sqrt{2})^{-1} - 1}{(B/\sqrt{2}) \nu} \right),
\]

\[\text{(4b)}\]

and
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\[ K_x \approx \frac{\rho f_u}{2\pi} \left\{ \sum_{j=1}^{n} D_j^1 D_j^2 \right\} \left( \frac{\pi^{-1} \tan^{-1} \left[ \frac{2B/\Gamma}{\sqrt{1-(4-(B^2/4\Gamma^2))}} \right]}{B/2\Gamma} \right) \]

Here, \( A_j^1, A_j^2 \) represents the amplitude of the \( j \)th line in the sinusoidal case, \( P_{j'}^t (P_{j'}^l, P_{j'}^c) \) represents the peak value of the Gaussian spectral distribution, and \( \gamma \) is its standard deviation, whereas \( D_j^1, D_j^2 \) and \( \Gamma \) represent the height and width of the Lorentzian spectrum, respectively. The index \( j \) ranges from 1 through \( n \), representing the number of line pairs permitted through the bandpass filter \( \Delta f = f_u \). After mixing with the LO, similarly, \( k \) ranges from 1 through \( m \). The quantity \( \delta \) is the error function. It has been assumed for simplicity that all spectral widths are identical, i.e., \( \gamma_j = \gamma \). \( \gamma_j+1 = \gamma \) and \( \gamma'_j = \gamma \). \( \Gamma_j = \Gamma \) and \( \Gamma_j+1 = \Gamma \). \( \Gamma = \Gamma \); similar but more complex expressions are obtained when this is not the case.

For quantum-noise-limited detectors such as photomultipliers and reverse-biased photodiodes operating in the infrared and optical, assuming that the incident radiation and the coherent LO are plane parallel waves polarized in the same plane, the input SNR to the nonlinear device is

\[ (\text{SNR})_i = \eta P_r / h \nu f_u, \quad h \nu \gg kT. \]  

Here \( \eta \) is the detector quantum efficiency, \( h \nu \) is the photon energy, \( kT \) is the thermal excitation energy (\( k \) is Boltzmann's constant and \( T \) is the detector temperature), and \( P_r \) is defined as the total received signal radiation power, i.e.,

\[ P_r = \sum_{j=1}^{n} P_j^t + \sum_{k=1}^{m} P_k^l. \]  

For Gaussian signals, the right-hand side of Eq. (6) should be multiplied by \( \sqrt{2\pi} \gamma \) whereas for Lorentzian signals the \( P_j^t \)s should be replaced by \( nD_j \)s. For photovoltaic detectors (e.g., HgCdTe or PbSnTe) and photoconductive detectors (e.g., Ge:Cu or Ge:Au), the input SNR is generally one-half that given in Eq. (5), as a result of additional generation-recombination (g-r) noise.

Heterodyne detectors in the microwave and millimeter-wave regions (\( h \nu \ll kT \)) include square-law mixers such as the crystal diode detector,

\[ \text{InSb photoconductive detector,} \]  

the pyroelectric detector,

\[ \text{the metal-oxide-metal diode,} \]  

and the bolometer. The latter three types of detectors have also been used successfully in the middle infrared (at 10.6\,\mu m)\textsuperscript{24-27}. Of particular interest in the millimeter and far-infrared regions are the low-noise fast Schottky-barrier diodes recently used in a number of experiments for astronomical observations\textsuperscript{28,29}. For this type of detector Johnson noise generally predominates, and the input SNR is given by

\[ (\text{SNR})_i = P_r / kT F_T f_u \]  

\[ = P_r / kT_{eff} f_u. \]  

For simplicity, we have lumped a number of detector parameters and operating conditions in the receiver noise factor \( F_T \) and in the receiver effective temperature \( T_{eff} \).

Thus, the output SNR is obtained by choosing a value of \( \rho \) and combining Eqs. (3)-(7). A number of further simplifying assumptions are possible, however, and we consider these in the next section.

IV. Further Approximations for the SNR and the MDP

We now consider the plausible case where each and every locally produced line \( f_j \), and its corresponding detected signal line \( f_j^t \) maintain a constant power ratio defined as \( \zeta \). Thus,

\[ \zeta(s) = A_j^2 / A_j^1 = A_j^{12} / A_j^{j+1}, \]  

\[ \zeta(g) = \gamma P_j / \gamma P_j^l = \gamma P_j / \gamma P_j^l, \]  

and
so that the expressions in large square brackets in Eq.(4) become

\[
\begin{align*}
\sum_{j=1}^{n} P_{j}^{2} & = \left[ \frac{\zeta}{(1+n)P_{0}^{2} + \lambda^{2}} \right]^{2} \\
\sum_{j=1}^{n} \sum_{k=1}^{n} P_{j}^{2} P_{k}^{2} & = \left[ \frac{\zeta}{(1+n)P_{0}^{2} + \lambda^{2}} \right]^{2} \left[ \frac{1}{(1+n)P_{0}^{2} + \lambda^{2}} \right]^{2} \\
\end{align*}
\]

Here, \( \overline{P_{j}} \) and \( \overline{P_{12}} \) represent the mean and mean-squared signal line power detected, respectively, and \( \overline{P_{0}} \) represents the mean impurity line power detected. For a single signal line \( n=1 \) and no impurity radiation \( m=0 \), Eq.(9) reduces to \( \zeta(1+n)^{-2} \) which, for \( \zeta = 1 \), is equal to 1/4. This result is the same as that provided by Eq. (9) of Ref. 4, as it should be.

Inasmuch as the quantities in large round parentheses in Eqs. (4b) and (4c) are of order unity for \( B \leq \gamma(\zeta) \), it is the larger of \( B \) and \( \gamma(\zeta) \) which limits \( \zeta \) and therefore the SNR in the Gaussian signal case. In particular, for the Gaussian spectrum case with \( B = \sqrt{8} \gamma(\zeta) \), \( 2\zeta(1)-1 = 0.68 \) whereas for the Lorentzian spectrum case with \( B = 4(\sqrt{2} - 1) \gamma(\zeta) \), \( \pi^{-1} \tan^{-1} 1 = 1/4 \). Thus the SNRs for the Gaussian and Lorentzian cases are reduced below that for the single wave case (delta-function spectrum), for the same bandwidth \( B \). This is understood to arise from the fact that some signal is being excluded in the Gaussian and Lorentzian cases in comparison with the delta-function case, but the noise is approximately the same. For fixed \( \gamma(\zeta) \), the best SNR for the Gaussian and Lorentzian cases is obtained as \( B \rightarrow 0 \), since the noise decreases faster than the signal, as \( B \) decreases, assuming that all of the center frequencies \( |f_{0} - f_{1}| \) precisely coincide. In actuality, however, the center frequencies are spread over the range \( (\gamma(\zeta)/c)[f_{0} - f_{1}] \leq \gamma(\zeta)/c \), and it is therefore not generally helpful to decrease \( B \) below this value. Small \( B \) does, however, provide a minor advantage in minimizing false signals from the \( K \) series, as we will see later.

For \( B \gg \gamma(\zeta) \), essentially all of the signal is included, and the results reduce to those obtained in the sinewave case. All other things being equal, then, these considerations dictate choosing lines for which the (Doppler) widths and, less importantly, the bandpass \( f_{u} a \cdot e \) minimized. Nevertheless, \( f_{u} \) should be sufficiently large to insure that several line pairs will be passed through the bandpass filter so that \( \overline{P_{12}} \) and \( \overline{P_{0}} \) will indeed benefit from the indicated averaging. Large \( f_{u} \), furthermore, provides small \( \text{SNR}_{0} \) and a simple expression for \( \text{SNR}_{0} \), as discussed in Section V. As we will see shortly, system performance in fact depends on the quantity \( f_{u}m \) rather than on \( f_{u} \) directly, so that the value chosen for \( f_{u} \) is reasonably arbitrary for a relatively dense population of lines.

The total received radiation power expressed in Eq.(6) may also be rewritten in terms of the ratio \( \gamma \) to provide

\[
P_{r} = \left( \frac{1}{(1+n)^{-1}} \right) \left( \frac{1}{(1+n)^{-1}} \right) \left( \frac{\zeta}{(1+n)^{-1}} \right) \left( \frac{\zeta}{(1+n)^{-1}} \right)
\]

where again we must include a factor of \( 2\sqrt{2\pi} \gamma \) in the right-hand side of Eq.(10) for Gaussian/Gaussian radiation and replace the \( P_{i} \) by \( \pi D_{i} \) for Gaussian/Lorentzian radiation.

For clarity, we now provide an explicit expression for \( \text{SNR}_{0} \), in the case of a Gaussian/Gaussian signal with the conditions and approximations expressed above. We conservatively choose \( f \approx 1 \) and consider a quantum-noise-limited detector. Using Eqs. (3), (4b), (5), (8b), (9), and (10), then, we obtain

\[
\text{(SNR)}_{0} = \left( \frac{\text{sn}^{2}}{\text{sn}^{2} + \text{sn}^{2}} \right) \left( \frac{\text{sn}^{2}}{\text{sn}^{2} + \text{sn}^{2}} \right) \left( \frac{\text{sn}^{2}}{\text{sn}^{2} + \text{sn}^{2}} \right) \left( \frac{\text{sn}^{2}}{\text{sn}^{2} + \text{sn}^{2}} \right)
\]

Further simplification occurs for the usual case when \( B \leq \gamma(\zeta) \), when the quantity in large round parentheses above is about 0.8. Finally, we make the assumption that \( \text{SNR}_{1} \ll 1 \), implying that signal-by-noise (s x n) terms are small in comparison with noise-by-noise (n x n) terms. This is
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a reasonable assumption for weak signals and for calculations of the minimum detectable power (MDP), and has the effect of making the denominator of Eq. (3) equal to unity. Incorporating these additional approximations in Eq. (11) provides the much simplified expression

$$\text{(S/N)}_0 = \frac{\sqrt{2} \nu f_u n (2/\sqrt{2\pi} \nu P^1)^2}{5\nu f_u^2 \nu^2}$$

(12)

The minimum detectable rms line power (MDP)_0 at the output of the system, is obtained by setting (S/N)_0 = 1 in Eq. (12) and solving for $$[(2/\sqrt{2\pi} \nu P^1)^2]^{1/2}$$. This yields

$$\text{(MDP)}_0 = \frac{h \nu}{n} \left( \frac{5 \nu f_u}{\sqrt{2} \nu n} \right)^{1/2}$$

(13a)

for quantum-noise-limited detection. Similarly, using Eq. (7) in place of Eq. (5) for Johnson-noise-limited detection, we obtain

$$\text{(MDP)}_0 \approx kT_{\text{eff}} \left( \frac{5 \nu f_u}{\sqrt{2} \nu n} \right)^{1/2}$$

(13b)

The substantive difference between Eqs. (13a) and (13b) here and Eqs. (13a) and (13b) of Ref. 4 lies in the presence of the factor $$\nu n$$; system detectability is seen to improve with increasing $$\nu$$ and increasing $$n$$ in the bandpass $$f_u$$. Of course, lines are counted only if both the remote and local samples contribute at a particular frequency. Defining $$\bar{f} = f_u/n$$ as the mean frequency interval between signal lines in the species whose presence we wish to affirm, and $$\nu$$ as the average linewidth, Eq. (13) may be rewritten as

$$\text{(MDP)}_0 = \frac{2h \nu}{\nu} \left( \frac{1}{\bar{f} f_u} \right)^{1/2}$$

(14a)

for quantum-noise-limited detection, and as

$$\text{(MDP)}_0 \approx 2kT_{\text{eff}} \sqrt{\bar{f} f_u}$$

(14b)

for Johnson-noise-limited detection. For simplicity, we have taken $$(\nu f_u)^{1/2} = 1.8803 \approx \nu$$ in Eq. (14). This expression represents the minimum average line radiation power required to be received for definitive detection. It indicates that small $$\nu$$ and large $$f_u$$ and $$\nu$$ are desired, and that $$\bar{f}$$ rather than $$f_u$$ is the important parameter, as indicated earlier. Thus, it will be easiest to detect a substance whose spectrum consists of a dense series of narrow lines that can also be made to radiate high power locally. For $$B \gg \bar{f}$$, $$\sqrt{\bar{f}} f_u^{1/2}$$ must be replaced by $$B f_u$$ in Eq. (14). We recall that it is not generally helpful to decrease $$B$$ below $$(\nu f_u/c) f_u$$, which is the center frequency spread. In a real system, furthermore, the sensitivity will be degraded below the ideal limits set forth above

V. Correction Factors for Impurity Species

The deleterious effect of the impurity frequency series $$K$$ on the SNR and MDP arises from both the $$s \times s$$ (signal-by-signal) and the $$s \times n$$ contributions to the output power spectral density. The calculation for the latter is straightforward and has been included in Eq. (3), through the factor $$[1+2(SNR)_i]$$ in the denominator. For small values of $$(SNR)_i$$, it is intuitively clear that the $$n \times n$$ contributions outweigh the $$s \times n$$ contributions, and the approximation following Eq. (11) suffices. The $$s \times s$$ contribution, on the other hand, arises from two distinct effects. The first represents the accidental occurrence of an $$f_k$$ line in a band of width $$B$$ about an $$f_j$$ or an $$f^*$$ line thereby mixing with this companion signal line to provide a false $$s \times s$$ component.

If we assume that both the $$f_j$$ and the $$f^*_k$$ lines are Poisson distributed in frequency, with rate parameters $$a$$ and $$b$$ respectively, an order-of-magnitude estimate for the average power in the $$s \times s$$ component due to this effect is proportional to $$4(1+\zeta)nbBP^2\gamma$$ (see Appendix B). Comparison with the true signal $$s \times s$$ contribution whose output power is proportional to $$\zeta n P^2$$ as given in Eq. (9), demonstrates that, at least for $$\gamma P = B$$, the correction factor may be ignored in the usual situation when $$B \ll 1$$ and $$\zeta > 1$$. If these conditions are not fulfilled, and/or if $$\gamma B$$, the correction must be applied, in which case this signal must be considered as a noise pedestal due to accidental coincidences and therefore subtracted from the measured signal. There are, however, accidental true signal contributions that reduce this deleterious effect (see Appendix B).

The second impurity effect contributing to the $$s \times s$$ term arises from frequency differences of lines in the $$K$$ series that accidently fall at $$[f_j-f_k]$$. Again making use of the Poisson assumption for the
frequency distribution of the \( f_n \) lines, it follows that the inter-frequency spacing distribution \( p(f) \) is gamma distributed in general, and for adjacent lines is exponentially distributed as \( b e x p(-bf) \) for \( f \geq 0 \). An estimate for the number of lines detected at such an accidental frequency separation, within \( B H a \) of \( |f - f_0| \), is \( <mbB \) (see Appendix B). The correction factor for the power, using the same proportionality constant as above, in this case is \( <mbB^{0.72} \) which can be of the same order of magnitude as the correction factor due to accidental coincidences. In many cases of practical interest, therefore, the previously presented results may be used without correction for impurity species.

VI. Discussion

A heterodyne correlation radiometer has been described for the sensitive detection of local and remote species such as pollutants, interstellar molecules, and trace minerals. It can also be used to measure isotopic abundances. The system operates on the basis of the fixed difference frequencies between the emission lines of a weak remote species and a locally radiating sample of that species. It introduces little loss over the conventional heterodyne radiometer, and can often provide a decreased noise bandwidth as well as a number of other specific advantages. The technique generally requires knowledge only of the Doppler shift of the remotely radiating source, and not of its emission frequencies, which are sometimes unknown or difficult to determine.\(^{30} \) It requires neither a stabilized nor a tunable LO. High-frequency response is demanded only of the heterodyne mixer and the nonlinear device; subsequent electrical signals are generated at (usually) moderate frequencies providing ease of matching, good receiver noise figure, and modest requirements for LO power. The technique is expected to be especially useful for the detection of remote or local species whose radiated energy is distributed over a large number of lines.

The ideal SNR and MDP at the output of the system have been obtained for a number of cases of interest, including sinusoidal signals and Gaussian signals with both Gaussian and Lorentzian spectra. Small linewidths and closely-space lines are seen to enhance detectability, as does a strongly radiating local sample. Of course, the remote source should be as strong as possible for definitive detection. Correction factors for impurity species have been accounted for and are not expected to seriously impair operation of the system. For certain choices of parameters, the SNR at the output of the heterodyne correlation radiometer will provide a sufficient confidence level for detection. For situations in which this is not the case, further improvement can sometimes be obtained by using a classical radiometer, a balanced mixer, and/or a multichannel receiver, as indicated previously. If the Doppler shift is unknown, for example, a multichannel receiver using a bank of narrow bandwidth filters can replace the single narrow bandpass filter (B), thereby substantially compressing the number of channels below that required in the conventional system. For the detection of multilobe radiation from astronomical sources, the real SNR will be reduced by a variety of deleterious effects in analogy with the conventional system.\(^{9} \)

The technique should operate over a broad frequency range from the microwave to the optical. For the detection of astronomical radiation, a possible candidate is the infrared emission from CO which exists in relatively high densities and with a very broad range of velocities in interstellar regions, as determined by its millimeter-wave emission.\(^{31, 32} \) Clearly, the same considerations apply to the detection of multiple-line maser radiation from astronomical sources\(^{33-36} \) and to the detection of remote pollutants.\(^{37, 38} \) The technique can only be used for sufficiently nonreactive substances that emit in the terrestrial laboratory as well as remotely, thus excluding, for example, \( \text{CN} \) and \( \text{C}_2\text{H}_2 \). Again we note that spectroscopic information about a molecule is not provided.

For the submillimeter region, it may be possible to use a combination Schottky-barrier-diode/harmonic-mixer that would provide an output at low frequencies as long as the high-frequency beat signals are generated and mixed within the detector. LO harmonics are also readily generated in these devices,\(^{28} \) so that harmonic-mixing heterodyne correlation radiometry could be performed\(^{41} \) Josephson junctions, which can sometimes be made to produce their own LO power,\(^{23} \) and metal-oxide-metal diodes could also be used. An IMPATT solid-state oscillator could conveniently be considered as an LO in these regions since frequency stabilization, which is difficult to achieve in these devices,\(^{23} \) is not required. At higher frequencies, some fixed-line lasers could possibly be used since the LO frequency need not be tunable.

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Appendix A

The expressions for $k_s$, $k_r$, and $k'_t$ presented in Eq.(4) can be obtained by generalizing the results given in Ref.2. We explicitly carry out the calculation for $k_s$; the results for $k_r$ and $k'_t$ follow by analogy.

We define $\omega_j = 2\pi|f_j - f_L|$, $\omega'_j = 2\pi|f'_j - f_L|$, and $\omega'_k = 2\pi|f'_k - f_L|$ and let $\varphi_j$, $\varphi'_j$, and $\varphi'_k$ represent the corresponding phase terms. The expressions for the detected $j$, $j'$, and $k'$ zero-mean electrical signals $s(t)$ sent to the square-law device can then be written as

$$s_j(t) = \sum_{j=1}^{n} A_j \cos(\omega_j t + \varphi_j),$$  \hspace{1cm} (A1a)
$$s'_j(t) = \sum_{j=1}^{n} A'_j \cos(\omega'_j t + \varphi'_j),$$  \hspace{1cm} (A1b)
and
$$s'_k(t) = \sum_{k=1}^{m} A'_k \cos(\omega'_k t + \varphi'_k),$$  \hspace{1cm} (A1c)
respectively. For simplicity, we have assumed that the heterodyne conversion constant $2\bar{B}A_L$ is absorbed in each signal coefficient $A$ ($\bar{B}$ is a proportionality constant containing the quantum efficiency of the detector and $A_L$ is the LO amplitude). The total input signal power, $(\text{Signal})_1$, arising from the $j$, $j'$, and $k'$ series, is therefore

$$(\text{Signal})_1 = \frac{1}{2} \left\{ \sum_{j=1}^{n} \left[ A_j^2 + A'_j^2 \right] + \sum_{k=1}^{m} A'_k^2 \right\},$$  \hspace{1cm} (A2)
and the signal-plus-noise input to the square-law device $x(t)$ may be written as

$$x(t) = s_j(t) + s'_j(t) + s'_k(t) + n(t).$$  \hspace{1cm} (A3)

In Eq.(A3), $n(t)$ represents the noise arising from the strong LO, and is therefore taken to be white Gaussian over the frequency band $[0,f_u]$. The input noise power, $(\text{Noise})_1$, is constant at $2f_u N$ so that the input signal-to-noise ratio, $(\text{SNR})_1$, is simply

$$(\text{SNR})_1 = \left\{ \frac{n}{2} \left[ \sum_{j=1}^{n} A_j^2 + \sum_{k=1}^{m} A'_k^2 \right] + \frac{1}{4f_u} \right\}/N.$$  \hspace{1cm} (A4)

Assuming that all terms in Eq.(A1) are independent with phases uniformly distributed over the interval $(0,2\pi)$, the associated autocorrelation functions are found to be

$$R_j(\tau) = E[s_j(t_1)s_j(t_2)] = \frac{1}{2} \sum_{j=1}^{n} A_j^2 \cos \omega_j \tau,$$  \hspace{1cm} (A5a)
$$R'_j(\tau) = E[s'_j(t_1)s'_j(t_2)] = \frac{1}{2} \sum_{j=1}^{n} A'_j^2 \cos \omega'_j \tau,$$  \hspace{1cm} (A5b)
and
$$R'_k(\tau) = E[s'_k(t_1)s'_k(t_2)] = \frac{1}{2} \sum_{k=1}^{m} A'_k^2 \cos \omega'_k \tau,$$  \hspace{1cm} (A5c)
where $\tau = t_1 - t_2$. The total power $\sigma^2$ contributed by each (zero-mean) series of lines is given by $R(0)$ so that

$$\sigma^2 = R_j(0) + \frac{1}{2} \sum_{j=1}^{n} A_j^2,$$  \hspace{1cm} etc.

The total input power is therefore represented as the sum of $R_j(0)$, $R'_j(0)$, and $R'_k(0)$; it is evident that the signal input power calculated from the sum of the autocorrelation functions is in agreement with Eq.(A2).

The output of the zero-memory square-law device $y(t)$ is, by definition,
\begin{equation}
\begin{aligned}
    y(t) &= \alpha x^2(t) \\
         &= \alpha [s^2(J) + s^2(K) + n^2(t) + 2s(J)s(K) + 2s(K)s(J) + 2s(J)n(t) + 2s(K)n(t) + 2s(J)n(t) + 2s(K)n(t)] \\
  \end{aligned}
\tag{A6}
\end{equation}

where \( \alpha \) is a scaling constant and we have used Eq. (A3). The expectation value \( E[\cdot] \) for \( y(t) \) is simply

\begin{equation}
\begin{aligned}
    E[y(t)] &= \alpha (E[s^2(J)] + E[s^2(K)] + E[n^2(t)]) \\
           &= \alpha (\tau^2_J + \tau^2_K + \tau^2_n) \\
  \end{aligned}
\tag{A7}
\end{equation}

for all \( t \), since the various processes in Eq. (A3) are independent. Thus, the autocorrelation function at the output of the square-law device is

\begin{equation}
\begin{aligned}
    R_y(\tau) &= E[y(t_1)y(t_2)] \\
              &= R_{JXJ}(\tau) + R_{J'XJ}(\tau) + R_{K'XK}(\tau) + R_{nXn}(\tau) + R_{JXJ}(\tau) \\
              &\quad + R_{J'XK}(\tau) + R_{J'XJ}(\tau) + R_{K'Xn}(\tau) + R_{J'XJ}(\tau) \\
  \end{aligned}
\tag{A8}
\end{equation}

where

\begin{equation}
\begin{aligned}
    R_{JXJ}(\tau) &= \alpha^2 R_{J^2}(\tau), \\
  \end{aligned}
\tag{A9a}
\end{equation}

\begin{equation}
\begin{aligned}
    R_{J'XJ}(\tau) &= \alpha^2 R_{J^2}(\tau), \\
  \end{aligned}
\tag{A9b}
\end{equation}

\begin{equation}
\begin{aligned}
    R_{K'XK}(\tau) &= \alpha^2 R_{K^2}(\tau), \\
  \end{aligned}
\tag{A9c}
\end{equation}

\begin{equation}
\begin{aligned}
    R_{nXn}(\tau) &= \alpha^2 R_{n^2}(\tau), \\
  \end{aligned}
\tag{A9d}
\end{equation}

\begin{equation}
\begin{aligned}
    R_{JXJ}(\tau) &= 4\alpha^2 R_{J^2}(\tau) + 2\alpha^2 \tau^2_J, \\
  \end{aligned}
\tag{A9e}
\end{equation}

\begin{equation}
\begin{aligned}
    R_{J'XJ}(\tau) &= 4\alpha^2 R_{J^2}(\tau) + 2\alpha^2 \tau^2_J, \\
  \end{aligned}
\tag{A9f}
\end{equation}

\begin{equation}
\begin{aligned}
    R_{K'XK}(\tau) &= 4\alpha^2 R_{J^2}(\tau) + 2\alpha^2 \tau^2_J, \\
  \end{aligned}
\tag{A9g}
\end{equation}

\begin{equation}
\begin{aligned}
    R_{nXn}(\tau) &= 4\alpha^2 R_{n^2}(\tau) + 2\alpha^2 \tau^2_n, \\
  \end{aligned}
\tag{A9h}
\end{equation}

\begin{equation}
\begin{aligned}
    R_{J'Xn}(\tau) &= 4\alpha^2 R_{J^2}(\tau) + 2\alpha^2 \tau^2_n, \\
  \end{aligned}
\tag{A9i}
\end{equation}

\begin{equation}
\begin{aligned}
    R_{K'Xn}(\tau) &= 4\alpha^2 R_{J^2}(\tau) + 2\alpha^2 \tau^2_n, \\
  \end{aligned}
\tag{A9j}
\end{equation}

and where

\begin{equation}
\begin{aligned}
    R_{J^2}(\tau) &= E[s^2(J,t_1)s^2(J,t_2)], \\
    R_{J^2}(\tau) &= E[s^2(J,t_1)s^2(J,t_2)], \\
  \end{aligned}
\tag{A9k}
\end{equation}

For clarity, we state explicitly the four assumptions used in arriving at Eqs. (A8) and (A9): (1) \( E[s(J)] = E[s'(J)] = E[s(K)] = E[n(t)] = 0 \); (2) The individual terms within each series are independent of each other; (3) The series \( J, J', \) and \( K' \) are independent of each other and of \( n(t) \); and (4) The system is stationary, time-invariant, and memoryless. Eqs. (A8) and (A9) are analogous to Eqs. (17) and (18) of Ref. 2, as may be seen by inspection.

To explicitly obtain all of the autocorrelation functions, we square and expand Eq. (A1a) to obtain
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\[
s_{j}^{2}(t) = \left\{ \sum_{j=1}^{n} A_{j} \cos(\omega_{j} t + \varphi_{j}) \right\}^{2}
\]

\[
= \sum_{j=1}^{n} A_{j}^{2} \cos^{2}(\omega_{j} t + \varphi_{j}) + 2 \sum_{j=1}^{n-1} \sum_{j'=j+1}^{n} A_{j} A_{j'} \cos(\omega_{j} t + \varphi_{j}) \cos(\omega_{j'} t + \varphi_{j'}) .
\]

Using Eqs. (A9) and (A10), and again assuming that all phase terms are uniformly distributed random variables over the interval \(0, 2\pi\), we obtain

\[
R_{JxJ}(\tau) = \alpha^{2} R_{J}(\tau) = \alpha^{2} E[s_{J}^{2}(t_{1}) s_{J}^{2}(t_{2})]
\]

\[
= \alpha^{2} \left\{ \frac{1}{4} \sum_{j=1}^{n} A_{j}^{4} + \frac{1}{2} \sum_{j=1}^{n-1} \sum_{j'=j+1}^{n} A_{j}^{2} A_{j'}^{2} + \frac{1}{8} \sum_{j=1}^{n} A_{j}^{4} \cos 2\omega_{j}\tau + \frac{1}{2} \sum_{j=1}^{n-1} \sum_{j'=j+1}^{n} A_{j}^{2} A_{j'}^{2} \cos(\omega_{j} + \omega_{j'})\tau + \frac{1}{2} \sum_{j=1}^{n-1} \sum_{j'=j+1}^{n} A_{j}^{2} A_{j'}^{2} \cos(\omega_{j} - \omega_{j'})\tau \right\} .
\] (A11)

All of these terms result from the vanishing contribution of the phases in their arguments; those portions of the expansion of \(s_{J}^{2}(t_{1}) s_{J}^{2}(t_{2})\) with phase terms in their arguments integrate to zero. A comparison of Eq.(A11) with Eq.(25) of Ref.2 is useful inasmuch as only cross terms display the factor \(1/2\) in both cases. \(R_{JxK}(\tau)\) and \(R_{JxK}(\tau)\) have expressions analogous to Eq.(A11); the formula for \(R_{JxK}(\tau)\) displays the subscript \(k\) in place of \(j\), undergoes summation to \(m\) rather than to \(n\), and has all \(A_{j}\)s primed, however.

Again using Eq.(A9), the autocorrelation function \(R_{JxJ}(\tau)\) is given by

\[
R_{JxJ}(\tau) = 4\alpha^{2} R_{J}(\tau) R_{J}(\tau) + 2\alpha^{2} \sigma_{j}^{2} \sigma_{j}^{2}
\]

\[
= \frac{1}{2} \alpha^{2} \left\{ \sum_{j=1}^{n} A_{j}^{2} A_{j}^{2} \cos(\omega_{j} - \omega_{j'})\tau + \sum_{j=1}^{n} A_{j}^{2} A_{j}^{2} \cos(\omega_{j} + \omega_{j'})\tau + \sum_{j=1}^{n-1} \sum_{j'=j+1}^{n} A_{j}^{2} A_{j'}^{2} \cos(\omega_{j} - \omega_{j'})\tau + \sum_{j=1}^{n} \sum_{j'=j+1}^{n} A_{j}^{2} A_{j'}^{2} \cos(\omega_{j} + \omega_{j'})\tau \right\}
\]

\[
+ \frac{1}{2} \alpha^{2} \left\{ \sum_{j=1}^{n} A_{j}^{2} \left( \sum_{j=1}^{n} A_{j}^{2} \right) \right\} .
\] (A12)

The critical terms are represented by the first or second summations, corresponding to the Doppler shift difference frequency \(|f_{j} - f_{j'}|\). Similarly, the expressions for \(R_{JxK}(\tau)\) and \(R_{JxK}(\tau)\) are

\[
R_{JxK}(\tau) = \frac{1}{2} \alpha^{2} \left\{ \sum_{j=1}^{n} \sum_{k=1}^{m} A_{j}^{2} A_{k}^{2} \cos(\omega_{j} + \omega_{k})\tau + \sum_{j=1}^{n} \sum_{k=1}^{m} A_{j}^{2} A_{k}^{2} \cos(\omega_{j} - \omega_{k})\tau + \left( \sum_{j=1}^{n} A_{j}^{2} \right) \left( \sum_{k=1}^{m} A_{k}^{2} \right) \right\} .
\] (A13a)

and

\[
R_{JxK}(\tau) = R_{JxK}(\tau) \bigg|_{J \rightarrow J'},
\] (A13b)

so that the total signal-by-signal autocorrelation function \(R_{SxS}(\tau)\) at the output of the square-law device is simply the sum

\[
R_{SxS}(\tau) = R_{JxJ}(\tau) + R_{JxJ}(\tau) + R_{JxK}(\tau) + R_{JxJ}(\tau) + R_{JxK}(\tau) + R_{JxK}(\tau) .
\] (A14)

Thus, after passing through the narrow bandpass filter centered at \(|f_{j} - f_{j'}|\) (and neglecting accidental contributions), the output signal power, \((\text{Signal})_{0}\), at the Doppler frequency is...
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\[
(Signal)_o = \frac{1}{2} \alpha^2 \sum_{j=1}^{n} A_j^2 A_j^2.
\] (A15)

The signal-by-noise autocorrelation function is obtained by using Eqs. (A5) and (A9h)-(A9j):

\[
R_{SN}(\tau) = R_{JXN}(\tau) + R_{J'XN}(\tau) + R_{K'XN}(\tau)
\]

\[
= 4 \alpha^2 R_n(\tau) [R_{J}(\tau) + R_{J'}(\tau) + R_{K'}(\tau)] + 2 \alpha^2 \gamma^2 \tau^2 \left( \sum_{j=1}^{n} A_j^2 \cos \omega_j^2 \tau + \sum_{j=1}^{n} A_j^2 \cos \omega_j^2 \tau + \sum_{k=1}^{m} A_k^2 \cos \omega_k^2 \tau \right) + 2 \alpha^2 \gamma^2 \tau^2 (\tau^2_{J'} + \tau^2_{K'}).
\] (A16)

Eq. (A16) demonstrates that \(R_{SN}(\tau)\) consists of a dc component, plus the autocorrelation function for noise modulated by the \(j\), \(j'\), and \(k\) signal terms. Inspection of Eq. (A16) leads to the following expression for the signal-by-noise power spectral density \(S_{SN}(f)\) at the output of the square-law device:

\[
S_{SN}(f) = \alpha^2 \sum_{j=1}^{n} A_j^2 \left[ S_n(f-f_j') + S_n(f+f_j') \right] + \alpha^2 \sum_{j=1}^{n} A_j^2 \left[ S_n(f-f_j') + S_n(f+f_j') \right] + 2 \alpha^2 \gamma^2 \tau^2 \left( \sum_{j=1}^{n} A_j^2 \right) \delta(f).
\] (A17)

This equation is analogous to Eq. (30) of Ref. 2 (in both cases \(\tau^2 = 2f_u N\)). Since the expression for \(S_n(f)\) is given by [see Eq. (24) of Ref. 2]

\[
S_n(f) = \begin{cases} 
N, & \text{for } 0 < |f| < f_n \\
0, & \text{elsewhere},
\end{cases}
\] (A18)

the signal-by-noise power spectral density is comprised of a series of steps symmetrically centered about zero frequency, with step heights \(\alpha^2 N A_j^2\), \(\alpha^2 N A_j^2\), or \(\alpha^2 N A_k^2\), depending on the particular frequency component \(j\) contained in \(S_n(f-F)\). The dc term is simply represented as a delta-function at \(f = 0\), so that a plot of \(S_{SN}(f)\) vs \(f\) would look similar to Fig. 4 of Ref. 2. Steps occurring near \(f = 0\) are from modulating frequencies close to \(f_u\), as do steps near \(\pm f_u\), whereas steps occurring near \(\pm f_u\) result from relatively low modulating frequencies.

The expression for \(S_{SN}(f)\) corresponds exactly to that given in Eq. (34) of Ref. 2, since the noise process is identical in both cases. Thus,

\[
S_{SN}(f) = 4 \alpha^2 f_u^3 N^2 \delta(f) + \begin{cases} 
2 \alpha^2 N^2 (2f_u - |f|), & \text{for } |f| < 2f_u \\
0, & \text{elsewhere},
\end{cases}
\] (A19)

Combining Eqs. (A15), (A17), and (A19) leads to a relatively simple expression for the final signal-to-noise ratio (SNR) \(\sigma\) at the output of the narrow bandpass filter of bandwidth \(B\) centered at \([f_f' - f_j]\):

\[
(SNR)_o = \frac{n \sum_{j=1}^{n} A_j^2 A_j^2}{8B \left[ 2f_u N + \sum_{j=1}^{n} A_j^2 + A_j^2 + \sum_{k=1}^{m} A_k^2 \right]}. \] (A20)

This relationship is analogous to Eqs. (37) and (41) of Ref. 2 and corresponds to the most conservative situation for which \([f_f' - f_j]\) \(\rightarrow 0\) and the SNR is minimum.

To achieve our stated goal we simply combine Eqs. (3), (A4), and (A20), and choose \(\rho = 1\) to arrive at Eq. (4a) for \(\kappa_{g}\). As indicated at the beginning of the Appendix, the results for \(\kappa_{g}\) and \(\kappa_{g}\) [presented in Eqs. (4b) and (4c), respectively] follow from parallel arguments.

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Appendix B

In this Appendix we explicitly obtain the correction factors for impurity species given in Section V of the text.

We first rewrite for reference the expressions for \( R_{J\times K'}(\tau) \), \( R_{J'\times K'}(\tau) \), and \( R_{J\times J'}(\tau) \) from Eqs. (A12) and (A13):

\[
R_{J\times K'}(\tau) = \frac{1}{2} a^2 \left\{ \sum_{j=1}^{n} \sum_{k=1}^{m} A_j^2 A_k^2 \cos(\omega_j + \omega_k) \tau \right. \\
+ \left. \sum_{j=1}^{n} \sum_{k=1}^{m} A_j^2 A_k^2 \cos(\omega_j - \omega_k) \tau \right\},
\]

(B1a)

\[
R_{J'\times K'}(\tau) = R_{J\times K'}(\tau) \bigg|_{J\rightarrow J'},
\]

(B1b)

and

\[
R_{J\times J'}(\tau) = \frac{1}{2} a^2 \left\{ \sum_{j=1}^{n} \sum_{j' \neq j} A_j^2 A_{j'}^2 \cos(\omega_j - \omega_{j'}) \tau + \sum_{j=1}^{n} \sum_{j' \neq j} A_j^2 A_{j'}^2 \cos(\omega_j + \omega_{j'}) \tau \right. \\
+ \left. \sum_{j=1}^{n} \sum_{j' \neq j} A_j^2 A_{j'}^2 \cos(\omega_j + \omega_{j'}) \tau \right\},
\]

(B2)

where \( \omega_j = 2\pi |f_j - f_L| \), \( \omega_k = 2\pi |f_j - f_L| \), and \( \omega_{j'} = 2\pi |f_{j'} - f_L| \).

The difference frequency terms in Eq. (B1) indicate that \( m \) lines in the \( K' \) series can combine with \( n \) lines in the \( J \) series to produce a total of \( mn \) lines. Only those lines lying within the bandpass of the narrowband filter centered at \( f_1 = |f_j - f_j'| \), however, will produce accidental noise contributions. If we consider a single \( f_j \) line, denoted \( f_j \), it is evident that all \( f_{j'} \) lines in the two frequency ranges

\[
f_c^* - B/2 < |f_j - f_{j'}| < f_c^* + B/2
\]

(B3) and

\[
f_c^* - B/2 < |f_j + f_{j'}| - 2f_L| < f_c^* + B/2
\]

(B4)

will contribute false signals. Inverting the inequalities (B3) and (B4) to obtain the critical frequency ranges where the mixing of \( f_{j'} \) and \( f_j \) will be detected, we find

\[
(f_j - f_c^*) - B/2 < f_{j'} < (f_j - f_c^*) + B/2,
\]

(B5a)

\[
(f_j + f_c^*) - B/2 < f_{j'} < (f_j + f_c^*) + B/2,
\]

(B5b)

\[
(2f_L - f_j - f_c^*) - B/2 < f_{j'} < (2f_L - f_j - f_c^*) + B/2,
\]

(B5c)

and

\[
(2f_L - f_j + f_c^*) - B/2 < f_{j'} < (2f_L - f_j + f_c^*) + B/2.
\]

(B5d)

Since the effective bandwidth represented by the four parts of Eq. (B5) is \( 4B \), it is clear that an average of \( 4nB \) (of a possible total of \( m \)) \( f_{j'} \) lines will deleteriously mix with \( f_j \). Extending this argument to all \( n \) of the \( f_j \) lines, the average number of accidental detections resulting from mixing of the \( K' \) and \( J \) series will be \( 4nbB \). Using Eqs. (A15) and (8a), along with the definition of \( F^{12} \) and a bit of algebra, we obtain

\[
\text{(Signal)}_o = 2\mu^2 n\zeta F^{12}
\]

(B6)

for the true signal output. Since the expected power per line due to the interaction of the \( K' \) and \( J \) series is \( 2\mu^2 F^{12} \), the accidental coincidence contribution for \( 4nbB \) lines is \( 8\mu^2 n\zeta F^{12} \). Adding to this the accidental coincidences resulting from the mixing of the \( K' \) and \( J' \) series, \( 8\mu^2 n\zeta F^{12} \), the total accidental coincidence power involving \( K' \) series mixing with \( J \) and \( J' \) is \( 8\mu^2 (1+\zeta) n\zeta F^{12} \). Dividing by the proportionality constant \( 2\mu^2 \) yields the relative factors \( n\zeta F^{12} \) for the true signal represented in Eq. (B6) and \( 4(1+\zeta) n\zeta F^{12} \) for the average \( \text{sx} \) component due to accidental mixing.
as indicated in the main text.

Assuming that the first summation in Eq. (B2) represents the desired signal, it is clear that there will be counterbalancing accidental coincidences that result from the two sum-frequency series and the remaining difference-frequency series in Eq. (B2). These coincidences are welcome, however, since they result from J and J' series mixing and therefore represent true but unexpected sxs contributions. The calculation of this effect is virtually identical to that performed earlier, with the substitution of a for b, \( \frac{P_a}{T} \) for \( \frac{P_b}{T} \), \( f' \) for \( K' \) in Eq. (B5), and (2n-1) for 2n for the accidental difference frequency terms. Thus, the accidental true sxs signal power contribution is \( 4\alpha^2(2n-1)aB\alpha^{\frac{P_a}{T}} \), resulting in a net expected accidental sxs power contribution given by \( 4\alpha^2B(2(1+n)aB\alpha^{\frac{P_a}{T}} - (2n-1)c\alpha^{\frac{P_a}{T}}) \). Extension to the Gaussian/Gaussian and Gaussian/Lorentzian cases is straightforward.

The second impurity effect discussed in Section V of the text arises from frequency differences in the K series that accidently fall at \( |f' - f| \). Under the assumption of a Poisson distribution of lines in a fixed frequency interval, the inter-frequency spacing obeys the well-known gamma density function

\[
p(f) = \frac{b}{(r-1)!} (bf)^{r-1} e^{-bf} , \quad f \geq 0 .
\]

(B7)

The parameter \( r \) represents the frequency interval to the \( r \)th line. Thus, the density function for the interval between adjacent lines (\( r=1 \)) is the simple exponential

\[
p(f) = be^{-bf} , \quad f \geq 0 .
\]

(B8)

The frequency range for which deleterious mixing of this second kind occurs is

\[
|f'_c - f_c| - B/2 < f < |f'_c - f_c| + B/2 .
\]

(B9)

Therefore, the probability that any two \( f'_c \) lines contribute a signal is, for fixed \( r \), a vertical ribbon of area under the gamma distribution represented in Eq. (B7), i.e.,

\[
Pr = \int_{|f'_c - f_c| - B/2}^{|f'_c - f_c| + B/2} \frac{b}{(r-1)!} (bf)^{r-1} e^{-bf} df .
\]

(B10)

For the usual situation, where \( B \) is much smaller than the width of the gamma distribution,

\[
Pr \approx \frac{bB}{(r-1)!} (bf'_c)^{r-1} e^{-bf'_c} .
\]

(B11)

It is not difficult to demonstrate that the number of adjacent lines that can mix is \( m-1 \) and in general, the number of lines separated by \( (r-1) \) intermediate lines that can mix, is \( m-r \). For each \( r \), therefore, the number of lines deleteriously mixing, \( N_r \), is expected to be

\[
N_r = (m-r) \frac{bB}{(r-1)!} (bf'_c)^{r-1} e^{-bf'_c} ,
\]

(B12)

and the over-all average number of lines deleteriously mixing for all \( r \), \( N_T \), is

\[
N_T = \sum_{r=1}^{m} N_r = \sum_{r=1}^{m} (m-r) \frac{bB}{(r-1)!} (bf'_c)^{r-1} e^{-bf'_c} .
\]

(B13)

For simplicity of expression, we upper bound the quantity \( N_T \) as follows:

\[
N_T < mbBe^{-bf'_c} \sum_{r=1}^{m} \frac{(bf'_c)^{r-1}}{(r-1)!} < mbBe^{-bf'_c} \sum_{r=1}^{m} \frac{(bf'_c)^{r-1}}{(r-1)!} = mbB .
\]

(B14)

The total power arising from K series accidental coincidences is therefore \( < 2\alpha^2 mbBe^{\frac{P_a}{T}} \), and again removal of the proportionality factor \( 2\alpha^2 \) results in the expression provided in the text. Finally, we note that lines from the J' series may also mix with themselves, resulting in a total J' series accidental power \( < 2\alpha^2 naB\alpha^{\frac{P_a}{T}} \). Since in general \( mb \gg na \), we do not account for this contribution. J' series self-mixing, which is undesirable, can generally be eliminated with appropriate instrumen-
tation. As in the case of deleterious mixing effects of the first kind, the extension to Gaussian/Gaussian and Gaussian/Lorentzian signals is readily made.

References