ENG ME/EC 501:

**Exercises (Set 4) (Due 10/23/18)**

1. Problem 3.1 in Friedland (next page).

2. Find standard “controllable” and “observable” realizations for the transfer functions given in Problem 3.2 in Friedland.

3. Problem 3.3 in Friedland. (N.B. you must assume $s_i \neq s_j$ for $i \neq j$.)
PROBLEMS

Problem 3.1 Exercises in resolvents and transition matrices

Find the resolvents and transition matrices for each of the following:

(a) \[ A_1 = \begin{bmatrix} -1 & 0 & 0 \\ 1 & -2 & 0 \\ 1 & 2 & -3 \end{bmatrix} \]

(b) \[ A_2 = \begin{bmatrix} -1 & 0 & 0 \\ 1 & -1 & 0 \\ 0 & 1 & -1 \end{bmatrix} \]

(c) \[ A_3 = \begin{bmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix} \]

Problem 3.2 Exercises on canonical forms

Determine the canonical forms (companion and Jordan) for each of the following transfer functions:

(a) \[ H(s) = \frac{(s + 2)(s + 4)}{(s + 1)(s + 3)(s + 5)} \]

(b) \[ H(s) = \frac{s + 2}{s[(s + 1)^2 + 4]} \]

(c) \[ H(s) = \frac{s + 3}{(s + 1)^2(s + 2)} \]

108 CONTROL SYSTEM DESIGN

![Tandem canonical form diagram]

Figure P3.3 Tandem canonical form.

Problem 3.3 Another canonical form

An alternative to the Jordan canonical form for single-input, single-output systems is the "tandem form" shown in Fig. P3.3.

(a) Write the \( A, B, \) and \( C \) matrices for this form.

(b) Given the system in Jordan form \( \dot{x} = Ax + Bu \) where \( A = \text{diag} \{ -s_1, -s_2, \ldots, -s_k \} \), find the transformation matrix \( T \) that transforms it to the tandem form.