

Supervised Autonomy: A Few Thoughts



Agile Autonomous Flight

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Fundamental issues:

How to find and prosecute targets in hostile, obstacle cluttered environments

What are appropriate roles for human operators? For aerial robots?



Tactical UAVs

- Large optics, high-quality sensors
- Altitude mitigates threats

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- Relatively large timescales
- Centralized, hierarchical control
- Separate task assignment and trajectory design





Munitions & MAVs

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- <u>Time critical targets</u>
- Non-typical targets at best, ATA cues
 'class' of potential targets → requires human
- Small optics, low-quality sensors
- High threat environment
- Robust search
- Small timescales



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Integrating Humans Into Time Critical Autonomous Systems

Time Criticality

- Human supervision effects of human response latency must be mitigated
 stability, robustness, performance
- Insight, not just oversight humans add value (e.g., situational awareness, judgement)

Context Appropriate Information Processing

 Information conveyed in appropriate context, at level of "cognition" required for decision

Operators must appreciate machine state at the "appropriate level" to make insightful decisions – machines supply <u>correct</u> information in <u>context</u> of situation

Machines must respond appropriately to operator decision processes in context of current situation and level of operator effectiveness – humans must supply (overtly or not) sufficient and timely information



This is a multi-scale dynamics & control problem:

- Humans are observers, exogenous dynamics, controllers, …
 - Humans impact system / subsystem stability, robustness, fragility, ...



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