

# Ec 703b: Problem Set 5

Mookherjee; Spring 2019

Due: Wednesday May 1

1. Consider the moral hazard model covered in class, but now the Principal is risk-averse, with a payoff function  $y(\pi - w)$  which is strictly increasing and strictly concave. The Agent A is also risk-averse with a payoff function  $v(w) - g(e)$  where  $v$  and  $g$  are both strictly increasing and  $v$  is strictly concave. All other assumptions are the same, i.e., (LLN) holds

(a) Set up the first-best problem where  $e$  is contractible. Characterize the optimal contract using Kuhn-Tucker conditions. Show that P and A must share risk: A's payment  $w_i^*(e^F)$  is strictly increasing in  $i$  (where  $\pi_i > \pi_{i-1}$  and  $e^F$  denotes the first best effort).

(b) Now consider the second-best problem where  $e$  is not contractible. As in class, assume there are two possible effort levels  $e_L < e_H$ , and  $v(\underline{w})$  is low enough that (LL) does not bind. Suppose the second-best effort is  $e_H$ . Characterize the optimal contract using Kuhn-Tucker conditions. Does the (IC) constraint bind? If it always does, provide a proof; otherwise find a condition for (IC) to bind.

(c) Show that in the second-best contract,  $w_i$  is always strictly increasing in  $i$  if MLRP holds.

(d) Does the second-best contract always satisfy the 'Informativeness Principle'?

2. Return now to the case where P is risk-neutral. Consider the moral hazard problem with three possible effort levels  $E = \{e_1, e_2, e_3\}$  and two possible profit levels,  $\pi_H = 10$  and  $\pi_L = 0$ . Let the probability of  $\pi_H$  given  $e$  be:

$$f(\pi_H | e) = \begin{cases} 2/3, & \text{if } e = e_1 \\ 1/2, & \text{if } e = e_2 \\ 1/3, & \text{if } e = e_3 \end{cases}$$

The agent's cost function for effort is

$$g(e) = \begin{cases} 5/3, & \text{if } e = e_1 \\ 8/5, & \text{if } e = e_2 \\ 4/3, & \text{if } e = e_3 \end{cases}$$

The agent's utility of wealth function is  $v(w) = \sqrt{w}$ . His reservation utility  $\bar{u}$  is zero.

(a) Show that if effort is not observable, then it is not possible to induce effort level  $e_2$ . (Notational suggestion: Let  $v_1 = v(w(\pi_H))$  and  $v_2 = v(w(\pi_L))$ .) For what values of  $g(e_2)$  can the principal induce effort level  $e_2$ ?

(b) What is the optimal contract when effort is not observable?