

Nonlinear Models

and

Hierarchical Nonlinear Models

Assumption of linearity

- The final assumption of linear models that we'll address is that of linearity
 - Recall that linearity of models is wrt parameters
- “Beastuary” of model from lecture 6 (Bolker ch 3)

Assumption of linearity

- Consider any arbitrary function / process model $y = g(x|\theta_m)$
 - Choose a data model
$$y \sim \text{PDF}(g(x|\theta_m), \theta_d)$$
 - If Bayesian, choose priors on θ_m & θ_d

Fitting nonlinear models

- Rarely an analytical solution
- Likelihood
 - Numerical optimization
 - LRT or Bootstrap error estimates & prediction
- Bayes
 - Metropolis-Hastings

Fitting nonlinear models

- Nothing you haven't seen / done before
- Nothing sacred about linear models

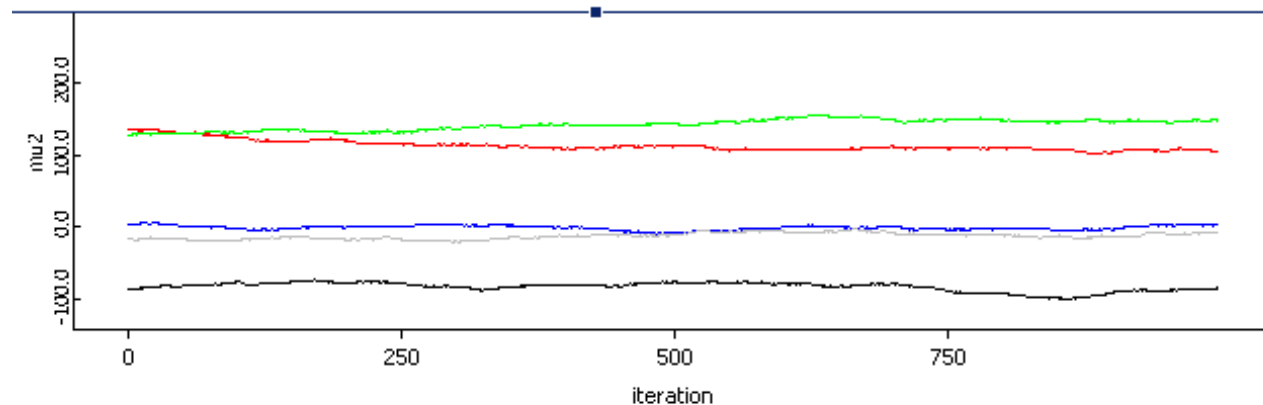
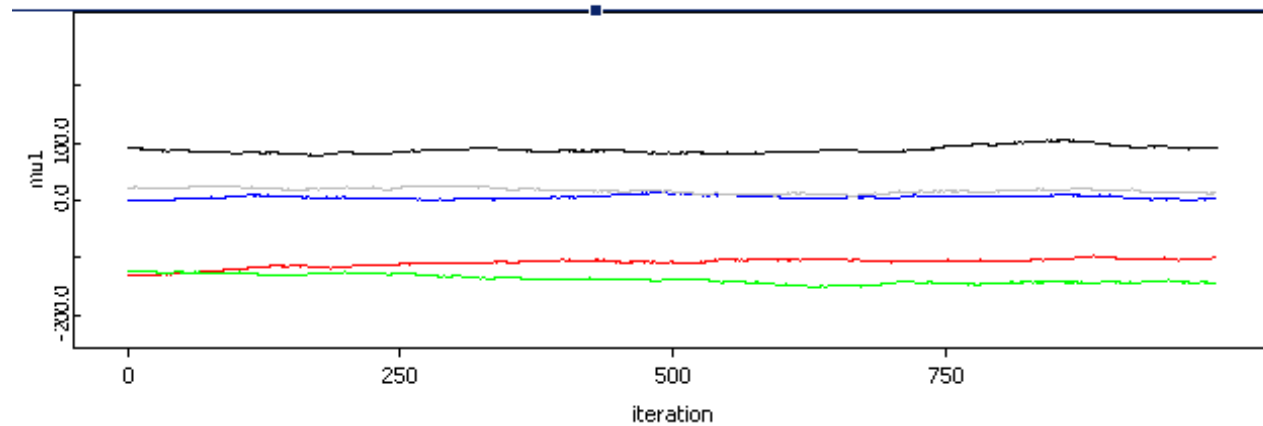
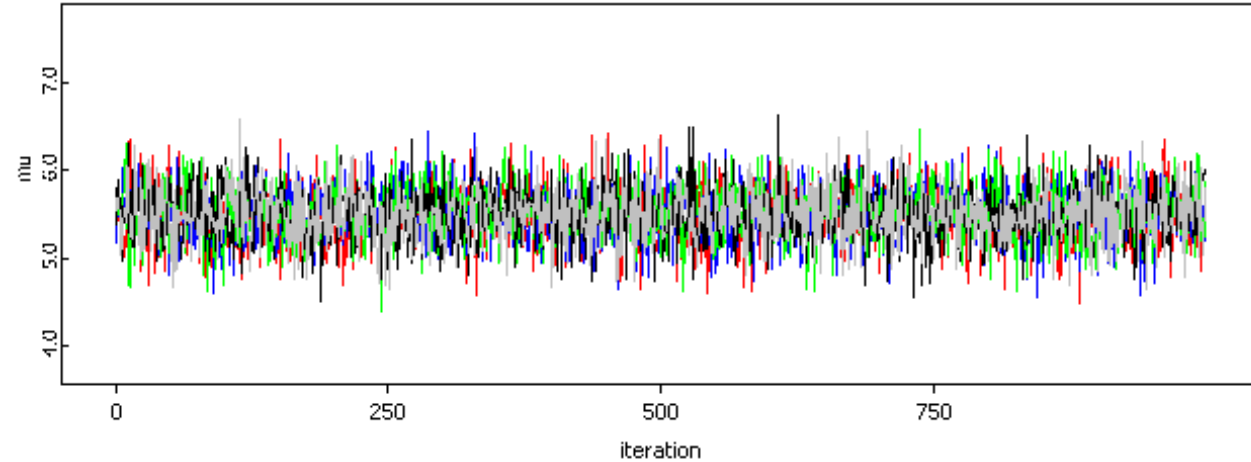
Things to watch for...

- Parameter identifiability
- Redundant parameters

$$Y = \frac{a}{b + cX}$$

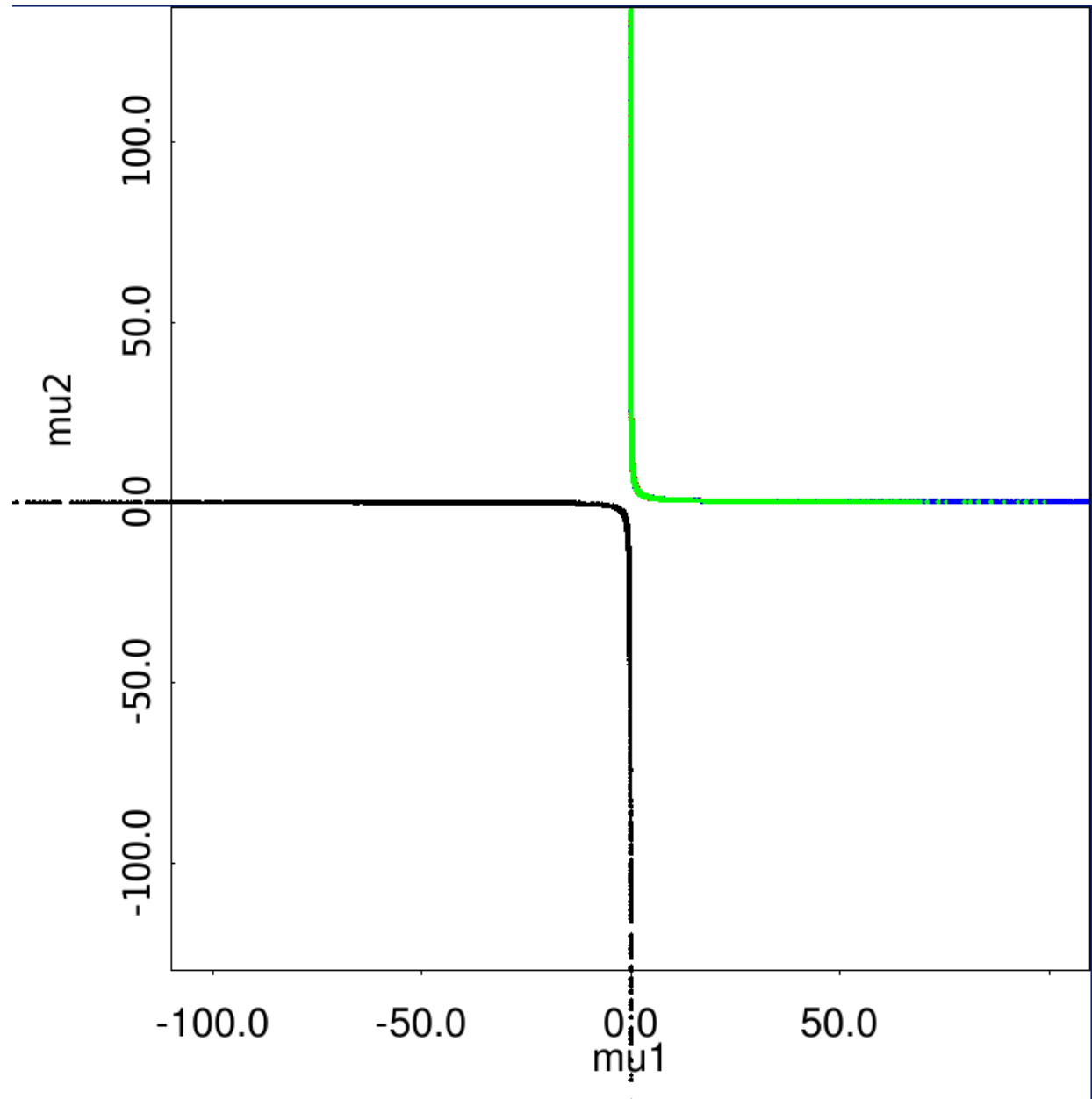


$$Y = \frac{1}{b' + c'X}$$



Things to watch for...

- Odd correlations between parameters



Nonlinear Hierarchical Models

- Often takes more thought to decide which parameters you consider random and which are fixed
- Setting all parameters to random can often result in unidentifiability
- Inclusion of covariates also challenging

Example: Coho salmon reproduction

- Beverton-Holt pop'n model with DD

$$r_t = \frac{s_t}{1/\alpha + s_t/r_m} e^{\epsilon_t}$$

- Consider
 - s = # of spawning Coho salmon
 - r = # of recruits
- Reproduction varies by stream?
 - How can we incorporate random stream effect?

Alternatives

$$r_{i,t} = \frac{S_t}{1/\underline{\alpha}_i + s_{i,t}/r_m} e^{\epsilon_{i,t}}$$

$$r_{i,t} = \frac{S_t}{1/\alpha + s_{i,t}/\underline{r}_{m,i}} e^{\epsilon_{i,t}}$$

$$r_{i,t} = \frac{S_t}{1/\underline{\alpha}_i + s_{i,t}/\underline{r}_{m,i}} e^{\epsilon_{i,t}}$$



$$r_{i,t} = \frac{S_t}{1/\alpha + s_{i,t}/r_m} e^{\epsilon_{i,t} + \underline{\theta}_i}$$

$$r_{i,t} = \frac{S_t}{1/\alpha_i + S_{i,t}/r_{m,i}} e^{\epsilon_{i,t}}$$

Process model

$$\epsilon_{i,t} \sim N(0, \sigma^2)$$

Residual error

$$r_{i,m} \sim N(\mu_r, \tau_r^2)$$

Stream-level
parameters

$$\alpha_i \sim N(\mu_\alpha, \tau_\alpha^2)$$

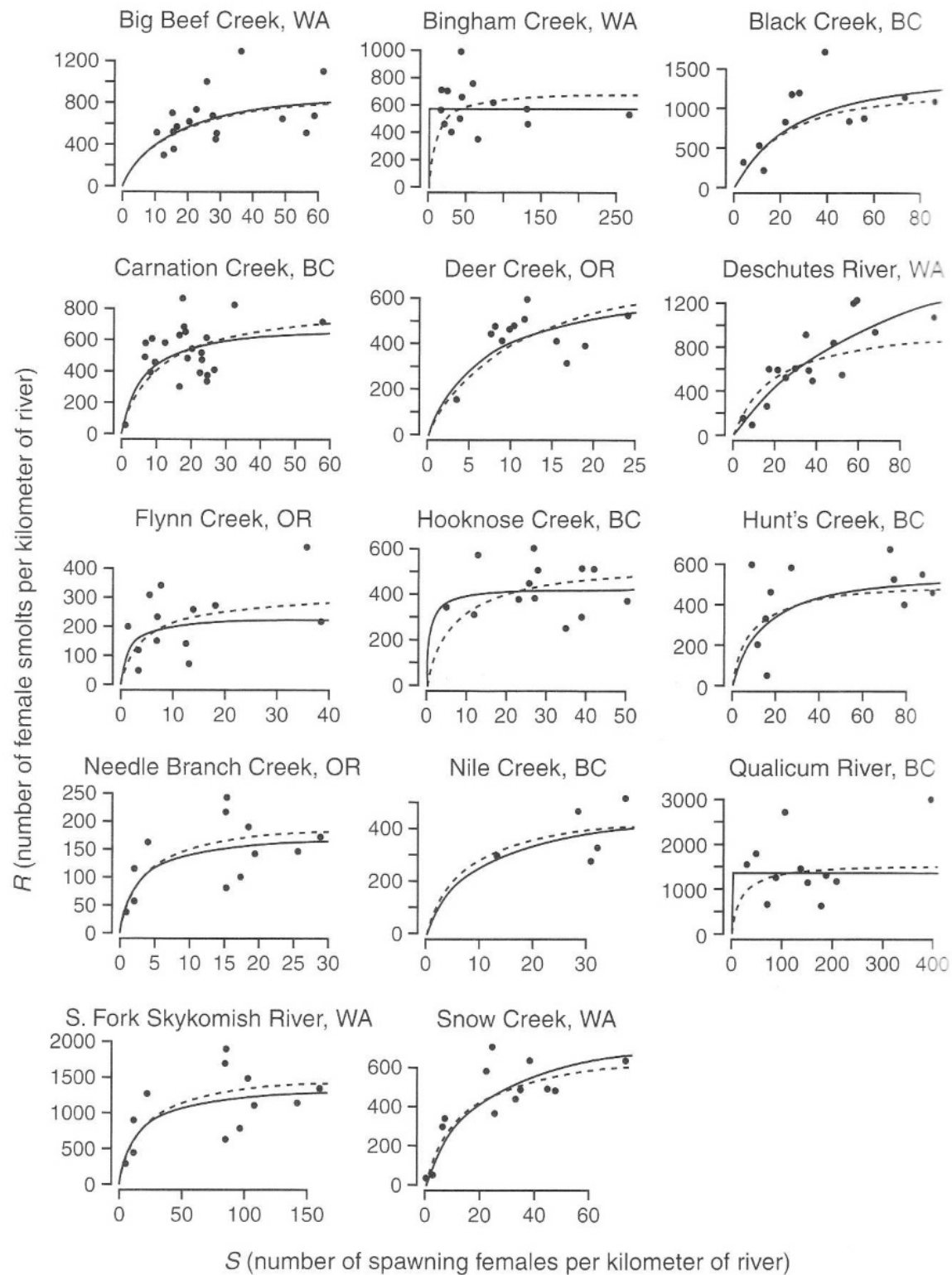
$$\mu_r \sim N(r_0, V_r)$$

Across stream
parameters

$$\mu_\alpha \sim N(\alpha_0, V_\alpha)$$

$$\tau_\alpha, \tau_r \sim IG(s_1, s_2)$$

Across stream
variance



Scale dependence in the effects of leaf ecophysiological traits on photosynthesis: Bayesian parameterization of photosynthesis models

Xiaohui Feng¹ and Michael Dietze²

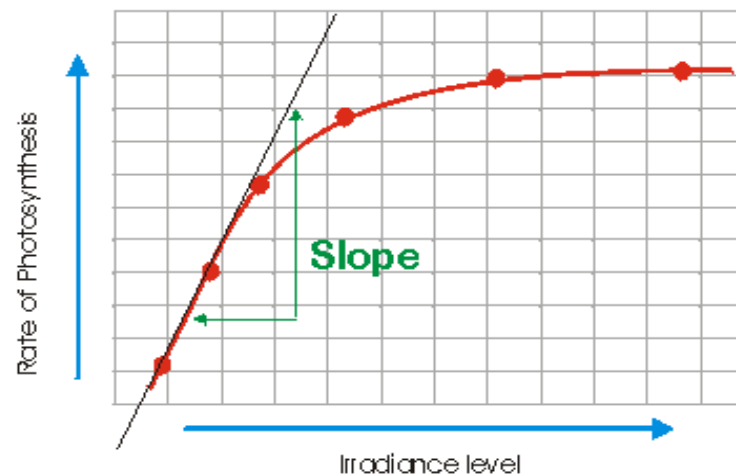
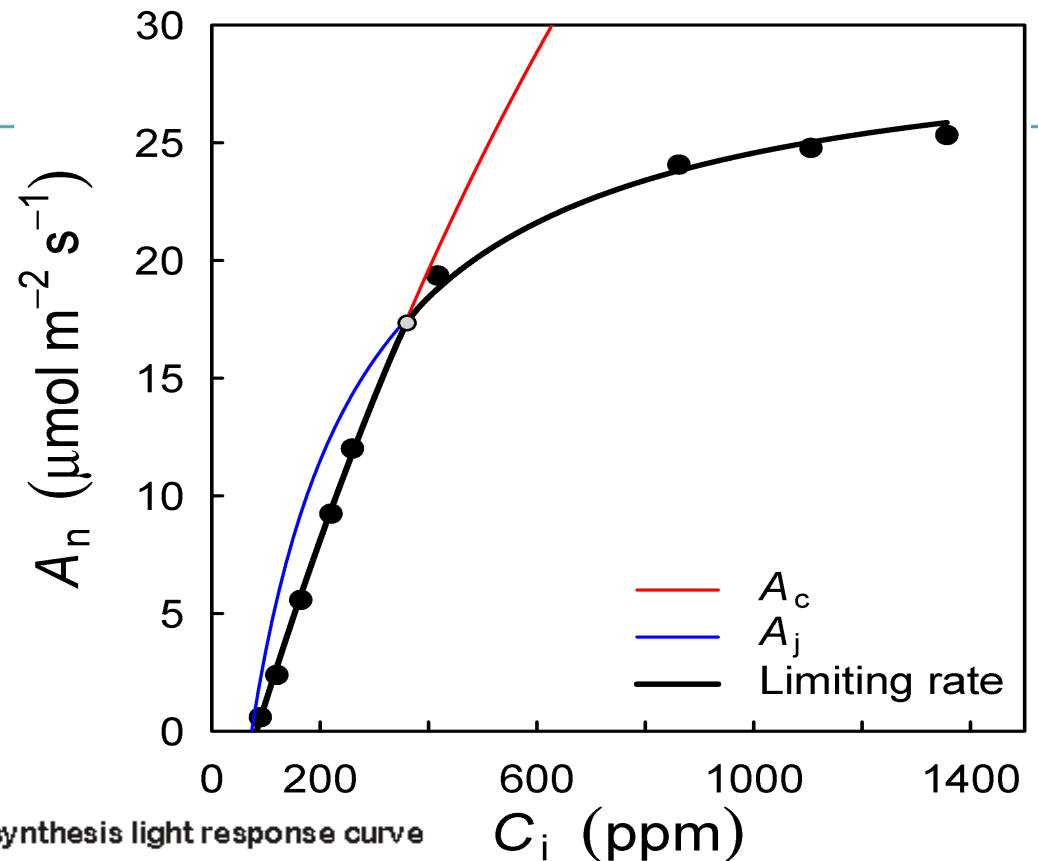
FvCB Model

$$A_n^{(m)} = \min\{A_v, A_j\} - R_d$$

$$A_v = V'_{\text{cmax}} \frac{C_i - \Gamma^*}{C_i + K_c \left(1 + \frac{O}{K_o}\right)}$$

$$A_j = \frac{J(C_i - \Gamma^*)}{4C_i + 8\Gamma^*}$$

$$J = \frac{\alpha' q}{\sqrt{\left(1 + \frac{\alpha'^2 q^2}{J_{\text{max}}^2}\right)}}$$



$$A_n^{(o)} \sim N(A_n^{(m)}, \tau^2)$$

$$A_n^{(m)} = \min\{A_v, A_j\} - R_d$$

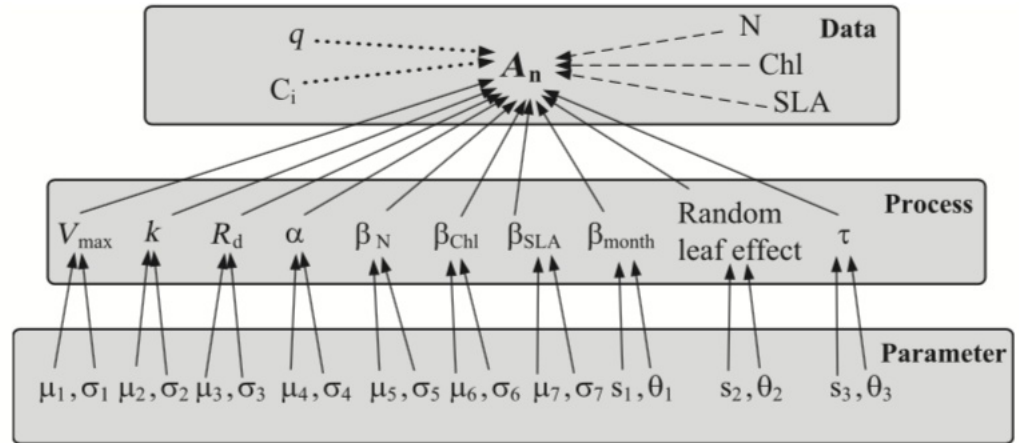
$$A_v = V'_{\text{cmax}} \frac{C_i - \Gamma^*}{C_i + K_c \left(1 + \frac{O}{K_o}\right)}$$

$$V'_{\text{cmax}} = \underline{V_{\text{cmax}} + \beta_N(N - \bar{N}) + \beta_{\text{mon}} + v_{\text{leaf}}}$$

$$A_j = \frac{J(C_i - \Gamma^*)}{4C_i + 8\Gamma^*}$$

$$J = \frac{\alpha' q}{\sqrt{\left(1 + \frac{\alpha'^2 q^2}{J_{\text{max}}^2}\right)}}$$

$$\alpha' = \underline{\alpha + \beta_{\text{Chl}}(\text{Chl} - \bar{\text{Chl}}) + \beta_{\text{SLA}}(\text{SLA} - \bar{\text{SLA}}) + \alpha_{\text{leaf}}}$$

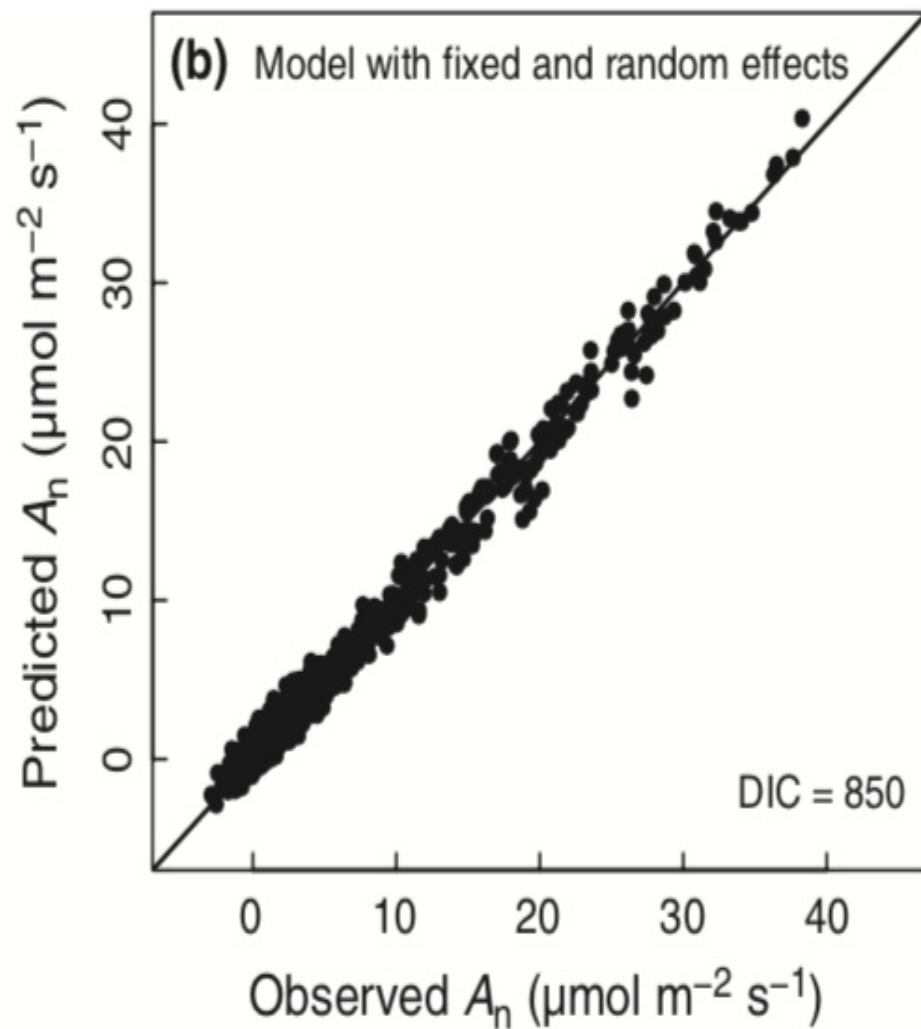
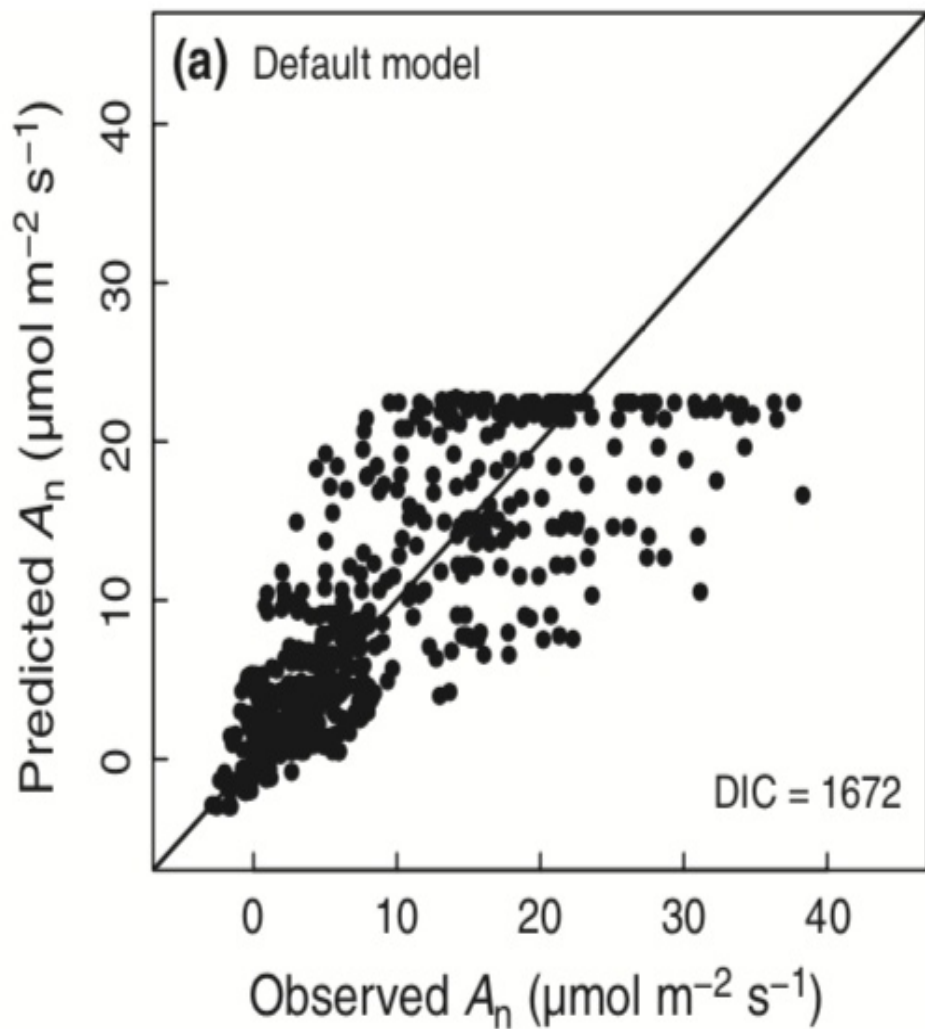


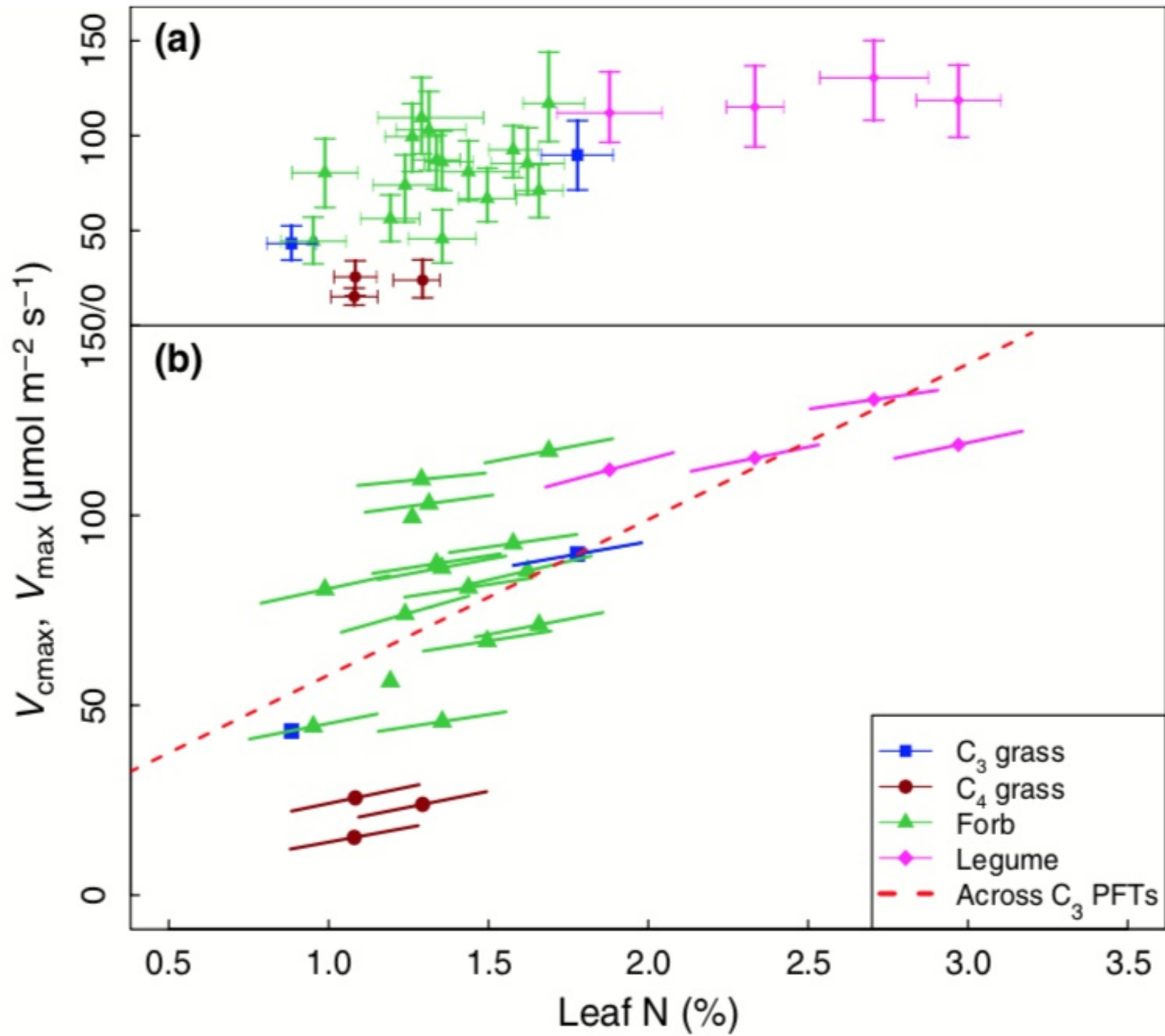
25 prairie species

2 years

Monthly (within growing season)

3-5 replicates/species





Example: CO2 effect on tree seedling growth

- i – seedling
- j – plot
- t – year
- l – light
- y - growth

$$y_{i,j,t} = \underbrace{\mu_{i,j,t}}_{\text{mean}} + \underbrace{k_t}_{\text{year}} + \underbrace{\epsilon_{i,j,t}}_{\text{residual}}$$

$$\epsilon_{i,j,t} \sim N(0, \sigma^2)$$

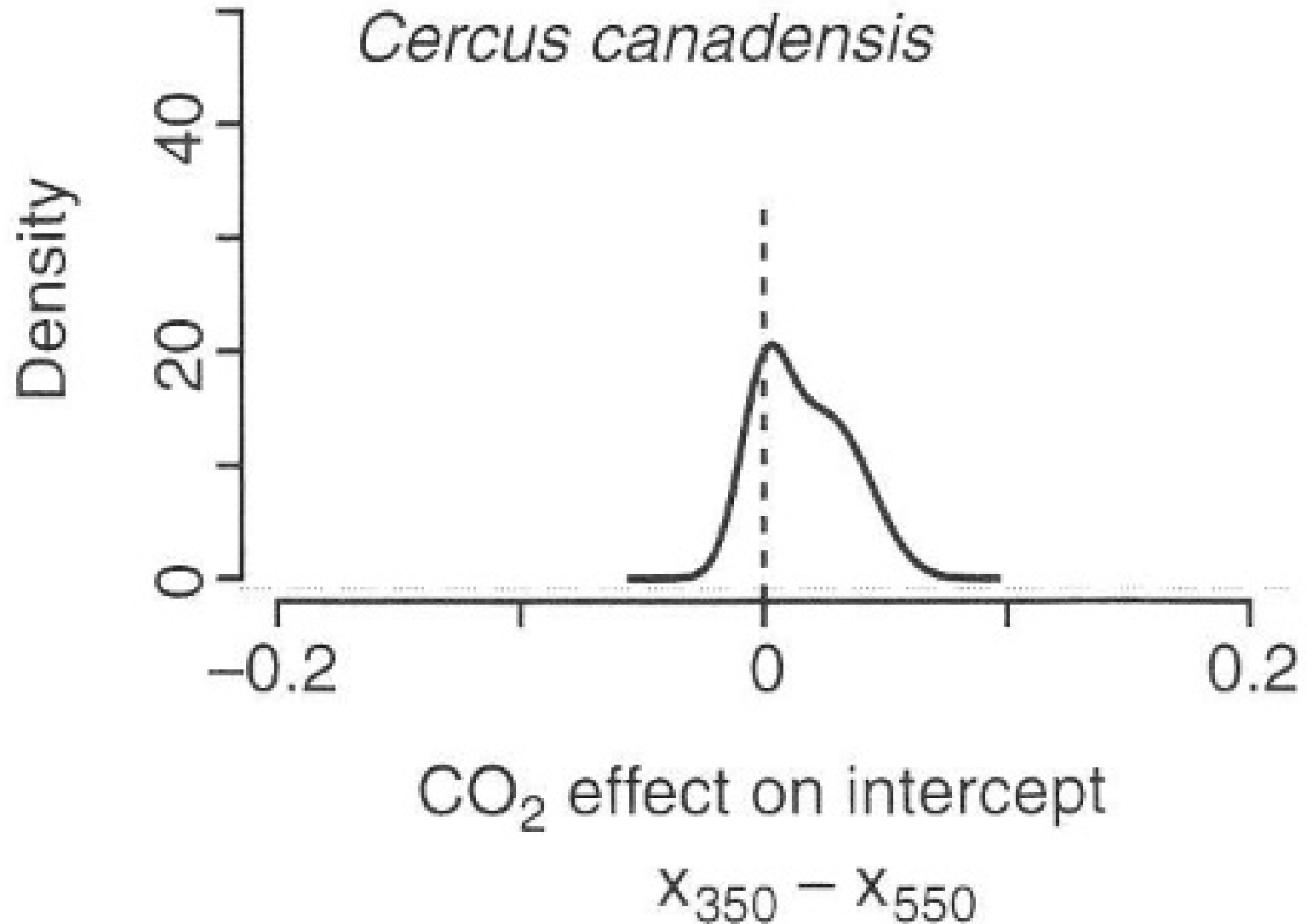
$$k_t \sim N(0, v_k)$$

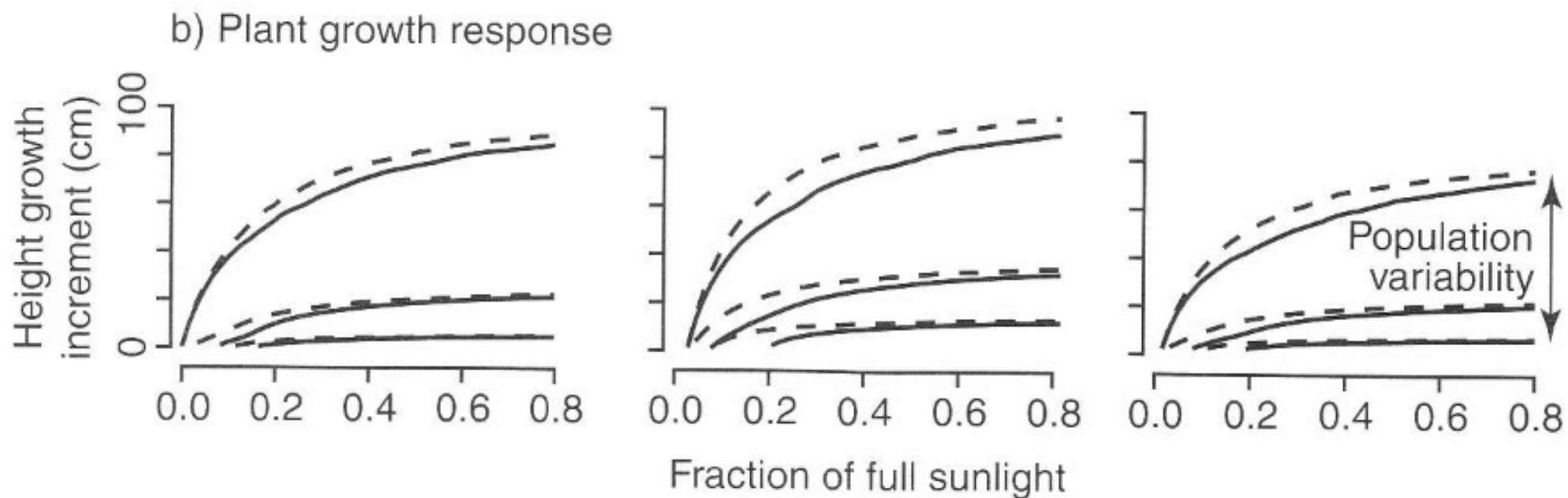
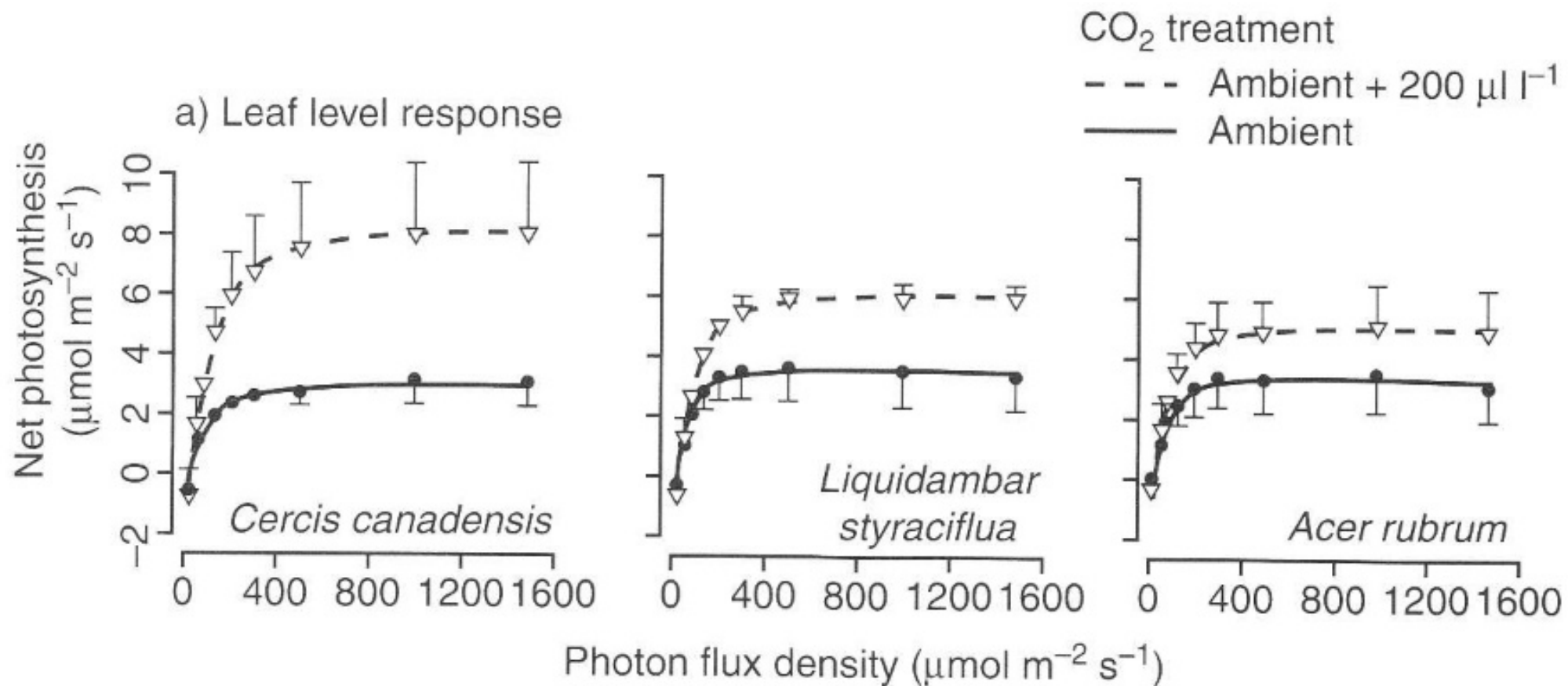
$$\mu_{i,j,t} = g_{i,j} \left(\frac{l_{j,t} - l_c}{l_{j,t} + \theta} \right)$$

$$g_{i,j} \sim \ln(\alpha, v_g)$$

l_c varies w/ CO2, Priors on ϵ , v_g , v_k , σ^2 , θ , l_c

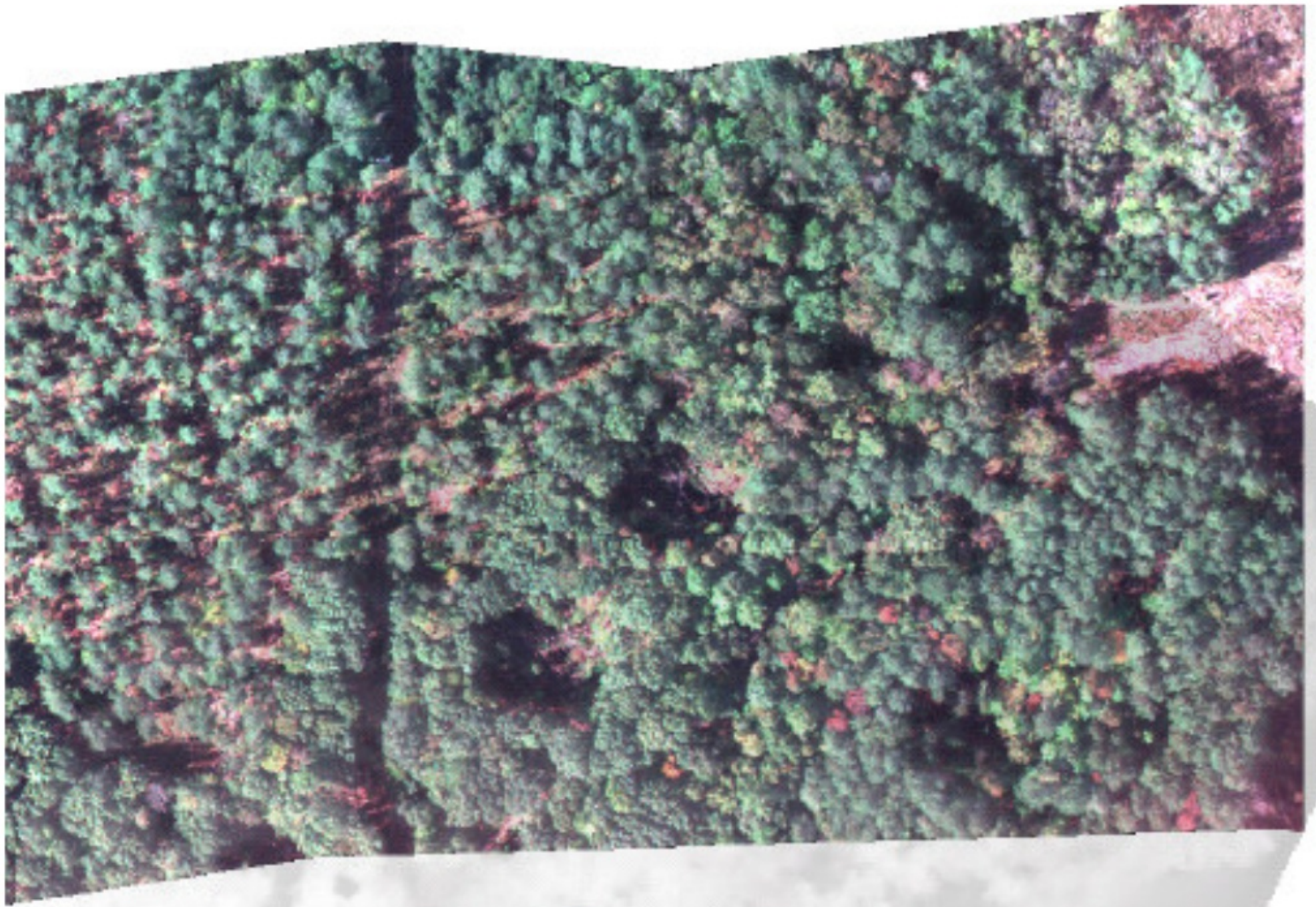
CO₂ effect



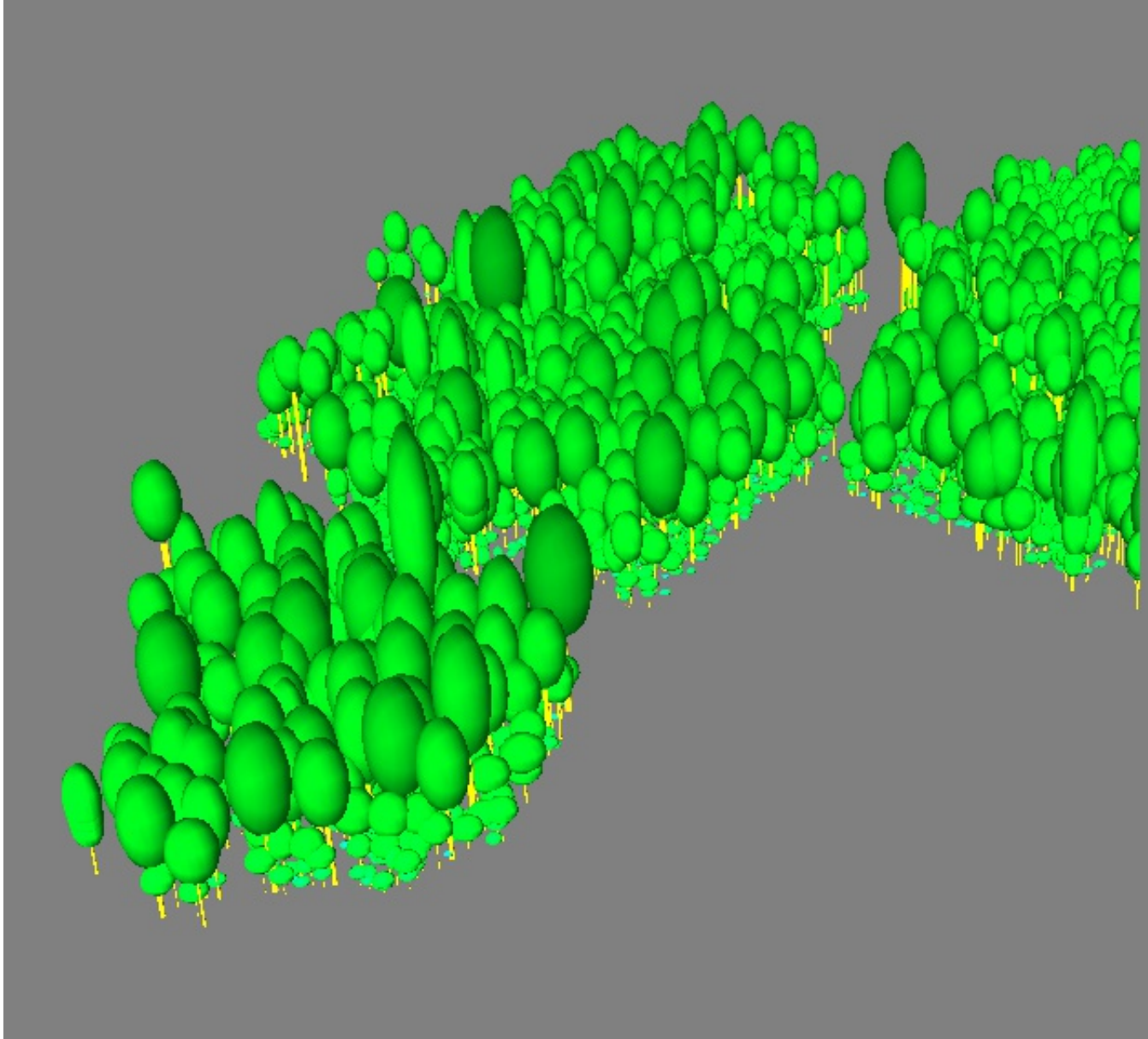


Canopy Light: Synthesizing multiple data sources

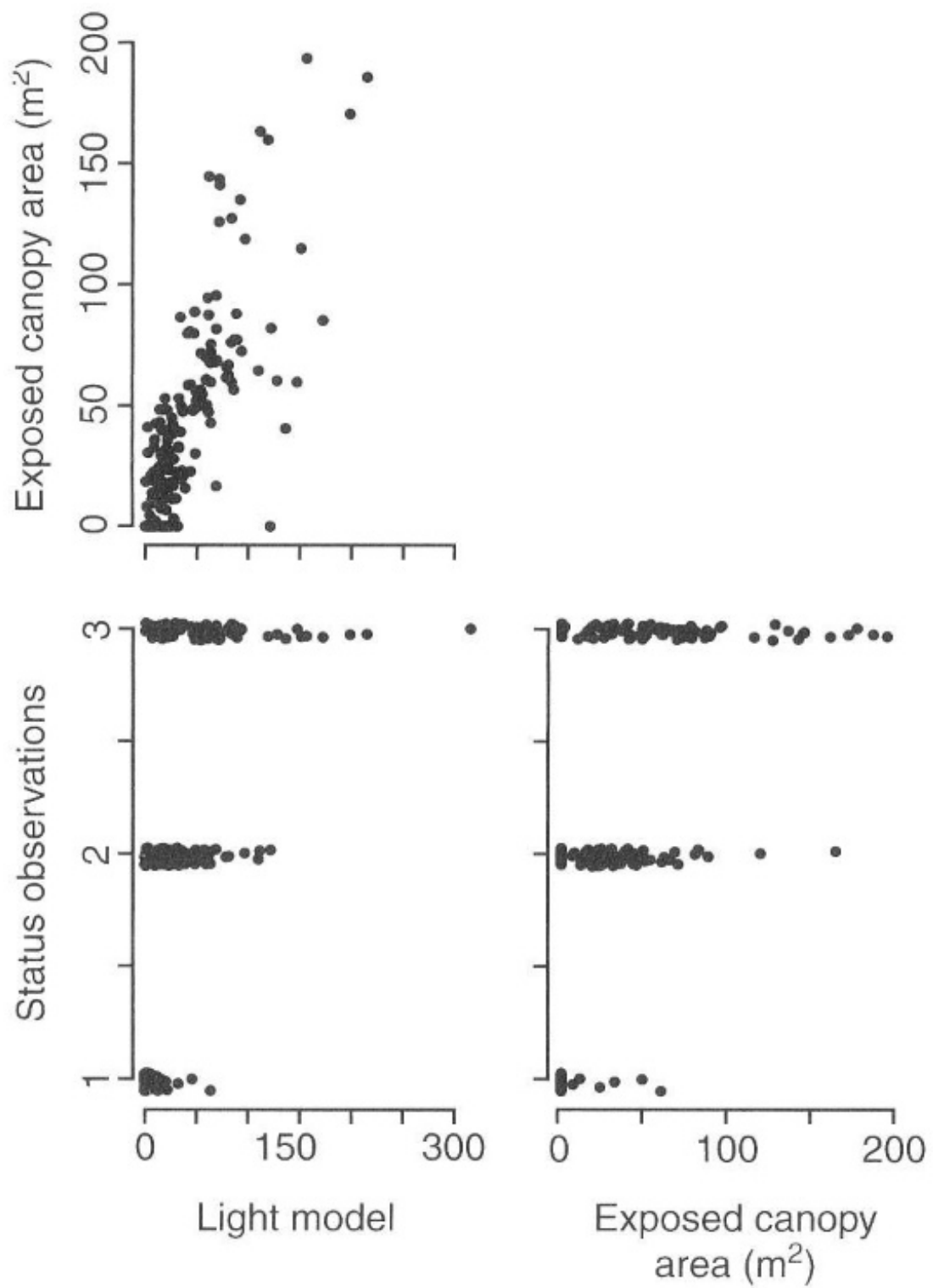
- Plant growth depends upon light (previous example, lab 7)
- Hard to measure how much light an ADULT tree receives
- Multiple sources of proxy data
 - Exposed Canopy Area
 - aerial photography, Quickbird
 - Canopy status
 - suppressed, intermediate, dominant (ex 8.2.2)
 - Light models
 - Allometries, stand map



Mechanistic Light Model



- Estimate light levels based on a 3D ray-tracing light model
- Parameterized based on canopy photos, tree allometries



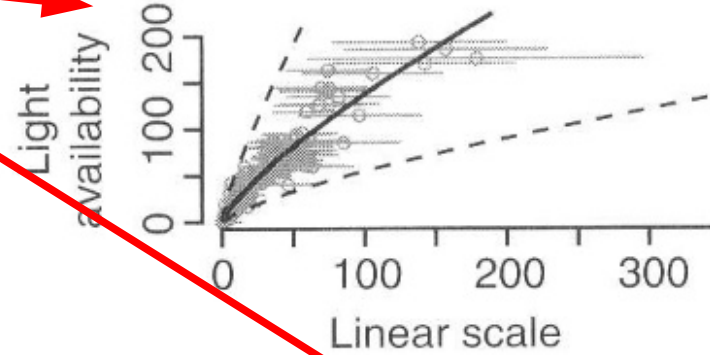
Linear models

Logistic

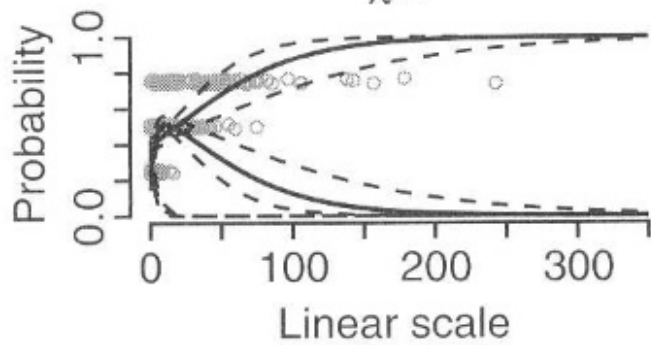
Multinomial

Non-zero ECA observations

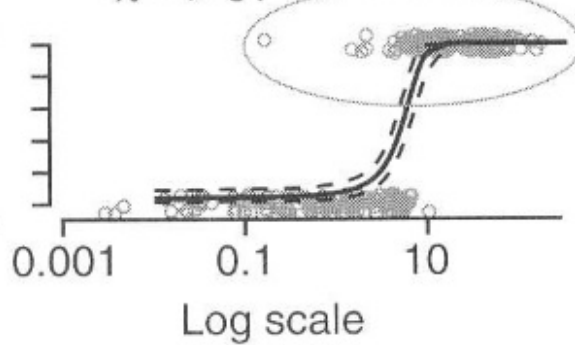
$\lambda^{(e)} > 0$



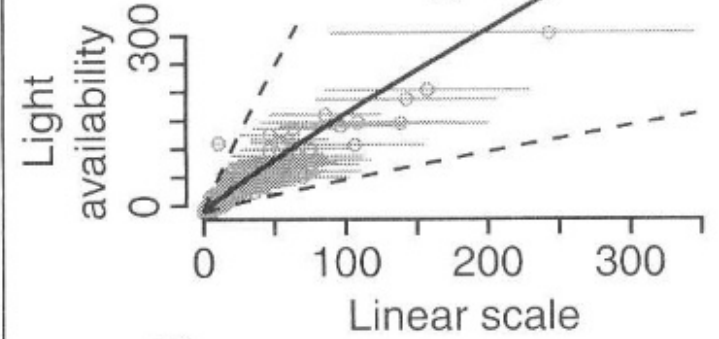
Status observations
 $\lambda^{(s)}$



Zero ECA observations
 $\lambda^{(e)} > 0?$



Model light estimate
 $\lambda^{(m)}$



$\beta_0 \beta_1$

c_0

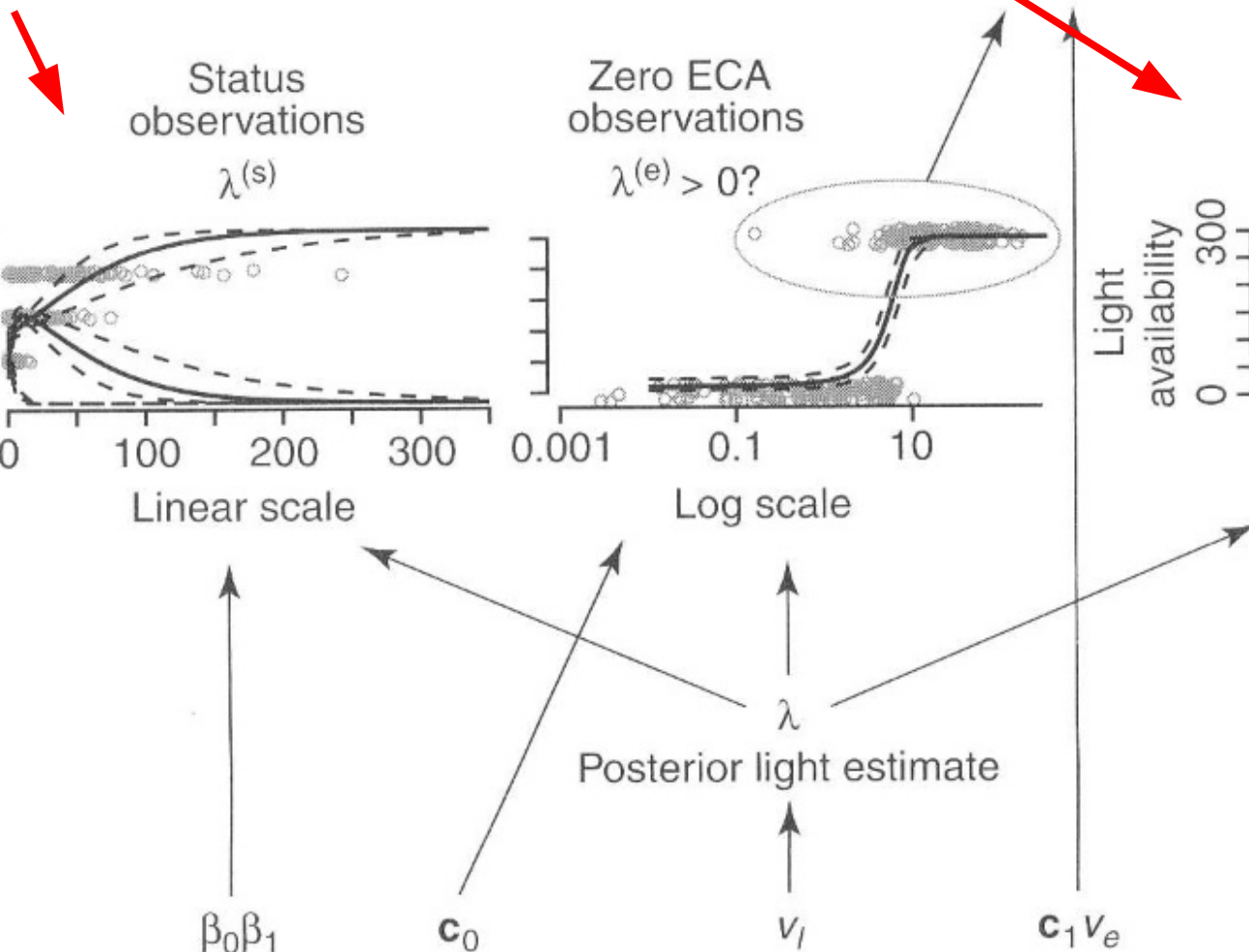
v_l

$c_1 v_e$

$a_0 a_1 v_m$

Posterior light estimate

λ



Exposed Canopy Area

- Error in relationship between “true” light λ and observations λ^e

$$p(\lambda_i^{(e)}) = \begin{cases} 1 - p_i & \lambda_i^{(e)} = 0 \\ p_i N(\ln(\lambda_i^{(e)}) | \ln(\lambda_i), v_e) & \lambda_i^{(e)} > 0 \end{cases}$$

- Probability of observing the tree in imagery increases with “true” light availability

$$\text{logit}(p_i) = c_0 + c_1 \lambda_i$$

Mechanistic Light Model

- Assume a log-log linear relationship between “true” light and modeled light
- Provides a continuous estimate of light availability for understory trees
 - ECA = 0
 - Status = 1

$$p(\lambda_i^{(m)}) = N(\ln(\lambda_i^{(m)}) | a_0 + a_1 \cdot \ln(\lambda_i), v_m)$$

Model Fitting

- Model fit all at once
- Find the conditional probabilities for each parameter (i.e. those expressions that contain that parameter)
 - Always at least 2 – likelihood and prior
 - Can be multiple likelihoods
- MCMC iteratively updates each parameter conditioned on the current value of all others