

## Problem 2

These exercises illustrate the fragility of social learning. They prepare for:

Frick, Mira, Ryota Iijima and Yuhta Ishii, (2020). “Misinterpreting Others and the Fragility of Social Learning,” *Econometrica*, 88, 2281-2328.

A. Recall the Vives model. Agent  $t$  has a payoff function  $-E[(\omega - x_t - \eta_t)]^2$ , where, to simplify here,  $\omega$  has diffuse prior (infinite variance), and  $\eta_t$  are independent normally distributed r.v. with mean  $b$  and precision  $\rho_\epsilon$ . Each agent has a signal  $s_t = \omega + \epsilon_t$  with  $\epsilon \sim \mathcal{N}(0, 1/\rho_\epsilon)$  as in the standard model.

Assume that agents are mistaken about the distribution of  $\eta$ . They believe that  $b = 0$  whereas the true value is positive.

1. Assume that agents optimize without looking at the history of past actions. Let  $\mu_t$  be the expected value of  $\omega$  for an outside observer, an econometrician, who knows the history of past actions,  $h_t = (x_1, \dots, x_{t-1})$ . Comment on the case  $b$  small.
2. Assume now that any agent  $t$  observe the history  $h_t$  of past actions. Analyze the evolution of  $\mu_t$ . Compare with the previous question. At some point, you may use the proposition of Vives (p. 8 of Notes 1).
3. (Optional). Simulate the evolution of  $\mu_t$  at a function of  $t$  for the particular realization of all noise terms equal to 0. (You may normalize other parameters to 1). Plot on a diagram the values of  $\mu_t$  and  $\rho_t$  (the precision of the estimate of  $\omega$  at the beginning of period  $t$ . Comment. (You may anticipate the answer in the previous question).
4. In view of your answer in question 2, what is the “flaw” in the the assumption about  $b$ , in that question? Is the exercise nevertheless informative? Comment.

B. Consider the model of social learning with two states, 0 and 1, two actions 0 and 1 with a cost of investment equal to  $c$ . The prior belief (probability of state 1) is  $\mu_1$ . Any agent  $t$  has a signal  $s_t = \theta + \epsilon_t$ , where  $\epsilon_t \sim \mathcal{N}(0, \sigma^2)$ . Assume that the true state is 1.

1. Does the belief converge? If yes, what is the limit? Does the sequence of actions eventually become a herd?
2. Assume now that in each round, with probability  $\pi$ , the acting agent is a “noisy” agent who does not invest, because his cost is greater than 1. Rational agents know the model and the probability  $\pi$ . Answer the previous question.
3. Assume that now that rational agents are not aware of the existence of noisy agents. (They think that  $\pi = 0$ ). To make the case interesting, assume that  $\pi$  is very small. Answer the previous question and comment on the case where  $\pi$  is very small. You may give an informal answer.